#### Tracking Dynamic Water-borne Outbreaks with Temporal Consistency Constraints

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#### **Problem Definition**

Given:

Network structure -Water Pipe System Noisy sensor readings at each node over time -False positive triggers (0.1) -True positive triggers (0.9)

**Identify**:

*Temporally consistent* subset of nodes that tracks a *dynamic pattern* spreading through the network.

Space-time scan statistics, Pattern detection, Sensor fusion



#### "Static" Method

Assumes the affected subset of nodes does not change over time. Constrained to search over spatial-temporal "cylinders".



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# Spatial-Temporal Overlap

Measures how well the detected subset covers the affected subset. It is a combination of precision and recall.



#### **Spatial Temporal Overlap**



# "Independent" Method

Allows the affected subset of nodes to change over time. Identifies an independent spatial subset for each time step.



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### **Temporal Consistency Constraints**

Let  $p_i^t$  be the prior probability that node *i* is included in the optimal subset at timestep *t*.

Let  $X_i^{t-1}$  be 1 if node *i* is included in the optimal subset at timestep *t*-1 and 0 otherwise.

We model the prior log-odds as:

$$\log\left(\frac{p_i^t}{1-p_i^t}\right) = \beta_0 + \beta_1 X_i^{t-1}$$

#### **Temporal Consistency Constraints**

$$\log\left(\frac{p_i^t}{1-p_i^t}\right) = \beta_0 + \beta_1 X_i^{t-1}$$

For example, if  $\beta_0 = -1.5$  and  $\beta_1 = 5$  then a node included in an optimal subset at timestep *t*-1 has a **97**% prior probability of being included in the optimal subset at time *t*.

A node that was *not* included at timestep *t*-1 has only a **18**% prior probability of being included in the optimal subset at time *t*.

#### From Independent to Dynamic



Initialize the spatial subsets independently



Randomly select a timestep t and its temporal neighbors t-1 and t+1

#### From Independent to Dynamic



Assign prior probabilities based on subsets t-1 and t+1



Recalculate optimal spatial subset incorporating temporal consistency



#### From Independent to Dynamic



Repeat this process until no changes improve the posterior probability of the resulting spatial temporal subset.

(convergence to a local maximum)

The resulting spatial-temporal subset of nodes and timesteps is returned as the detected subset for the "Dynamic" method.

#### **Spatial Temporal Overlap**



#### Temporal Consistency Constraints and Neighbors

Let  $n_i^{t-1}$  be the number of neighbors of node *i* included in the optimal subset at timestep *t-1* and  $k_i$  be the degree of node *i*.

Then neighboring nodes can influence the prior probability as well.

$$\log\!\left(\frac{p_i^t}{1 - p_i^t}\right) = \beta_0 + \beta_1 X_i^{t-1} + \beta_2 \frac{n_i^{t-1}}{k_i}$$

#### Spatial Temporal Overlap for FPR = 0.2 and TPR = 0.8



The "Dynamic" method detects plumes approximately ½ hour earlier than the "Static" method with one false alarm per month.

#### Conclusions

Relaxing constraints on spatial-temporal region shape must be done carefully:

Hard constraints on the spatial-temporal region fails to capture the dynamics of the pattern.

Independent selection of spatial subsets loses important temporal information.

Incorporating temporal consistency constraints addresses these issues and results in higher spatialtemporal accuracy and detection power.

# Thank You

References:

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