

Small Area Spatiotemporal Crime Rate Forecasting

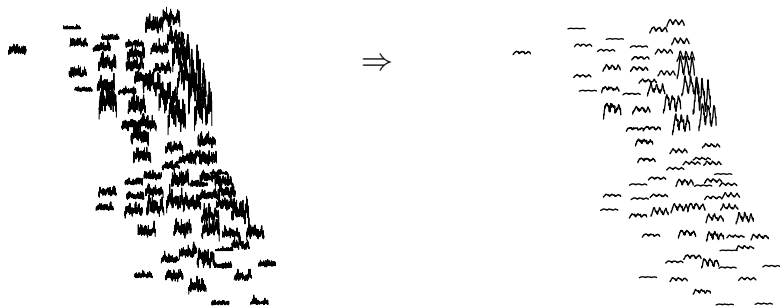
William Herlands

Carnegie Mellon University

November 19, 2015

Road map

- ▶ Forecasting and prediction of crime rates
- ▶ Bayesian modeling framework
- ▶ Theft in Chicago
- ▶ Experimental results

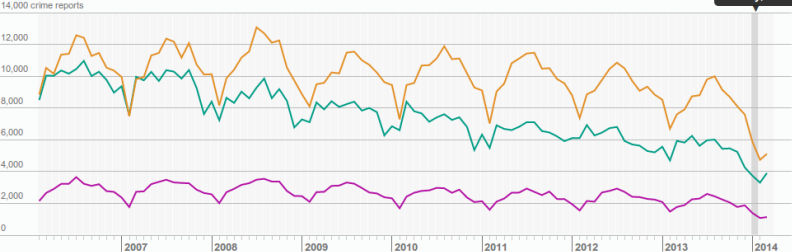


Crime rates: temporal

Crime in Chicago by month, 2006 to present

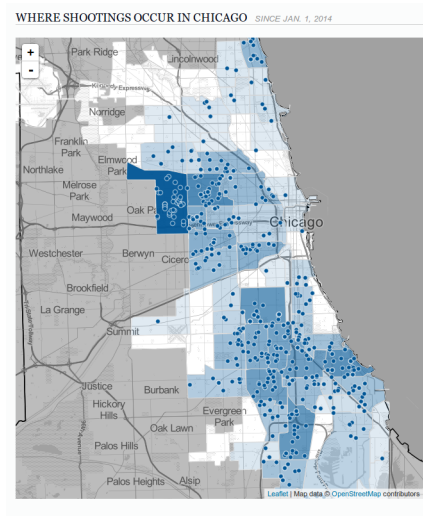
Hover to see totals

VIOLENT CRIMES 1,392 **PROPERTY CRIMES** 5,881 **QUALITY OF LIFE CRIMES** 3,740



source: crime.chicagotribune.com

Crime rates: spatial



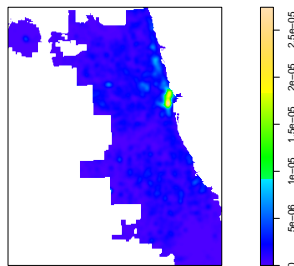
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Previous Work

- ▶ Univariate time series models [Gorr, Olligschlaeger, Thompson 2003]

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- ▶ “Heat maps” [Groff and La Vigne, 2002, many others], “risk terrain modeling” [Caplan and Kennedy, 2011]



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- ▶ Forecasting: better out-of-sample performance (MSE) compared to existing methods, with forecast intervals

Modeling framework: Gaussian Processes

Bayesian framework for specifying priors over functions

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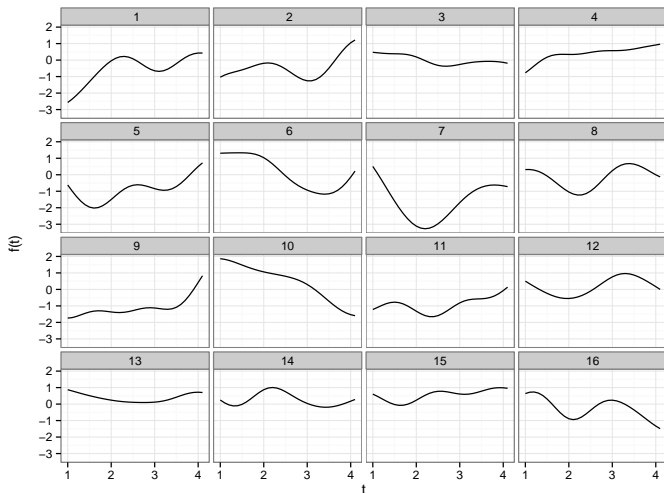
Bayesian framework for specifying priors over functions

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Gaussian Processes

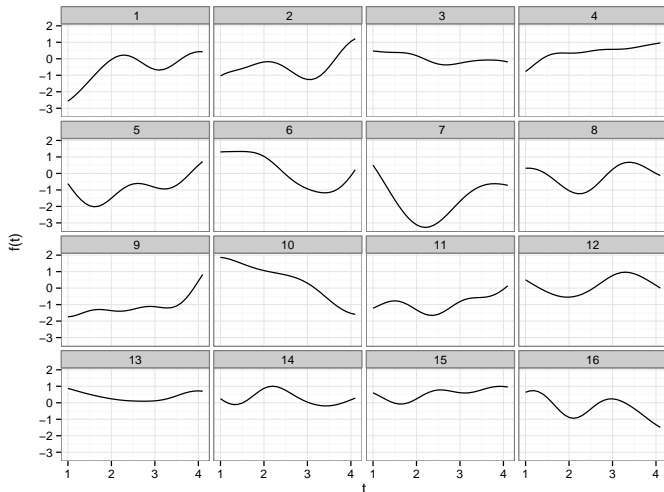
- ▶ Covariance function specifies smoothness of function:

$$f(t) \sim \mathcal{GP}(0, k(t, t')), \quad k(t, t') = \exp(-|t - t'|^2)$$

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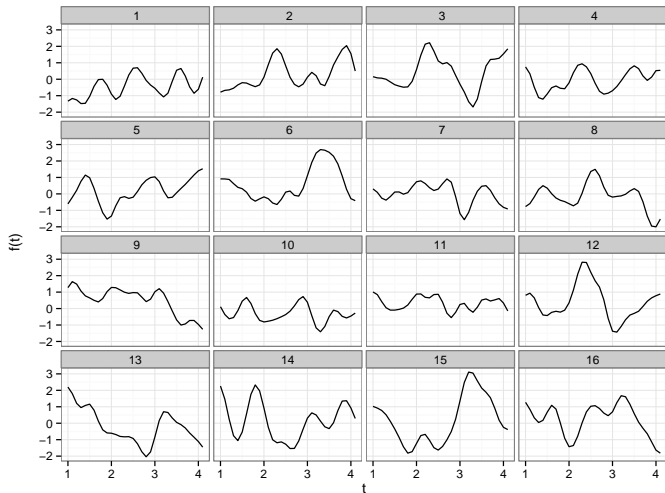
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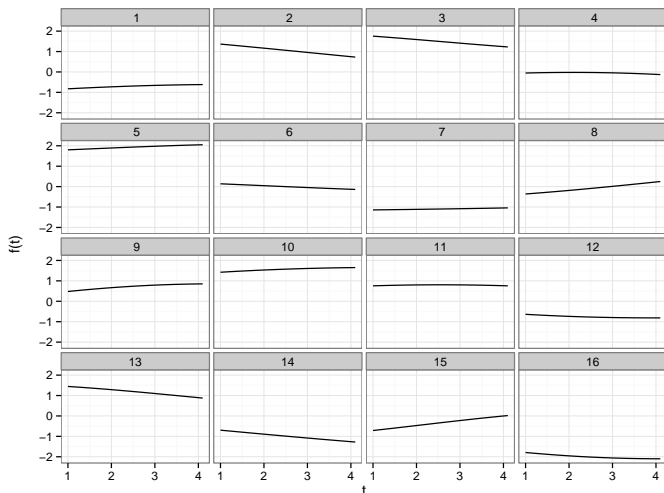
$$f(t) \sim \mathcal{GP}(0, k(t, t')), \quad k(t, t') = \exp\left(-\frac{1}{0.01}|t - t'|^2\right)$$



Gaussian Processes

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$$f(t) \sim \mathcal{GP}(0, k(t, t')), \quad k(t, t') = \exp\left(-\frac{1}{10}|t - t'|^2\right)$$



Gaussian Processes for Count Data

- ▶ At space-time location (s, t) :

$$n_{s,t} \sim \text{Poisson}(\lambda(s, t))$$

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- ▶ Place a GP prior on the log-intensity:

$$f(s, t) \sim \mathcal{GP}(0, K)$$

Recap and Preview: Gaussian Processes

- ▶ Fully Bayesian framework: uncertainty intervals for all parameters, predictions, and forecasts

Recap and Preview: Gaussian Processes

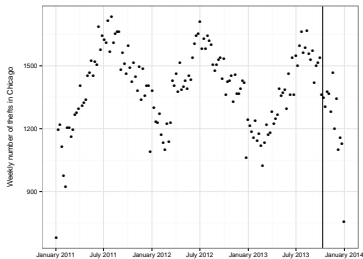
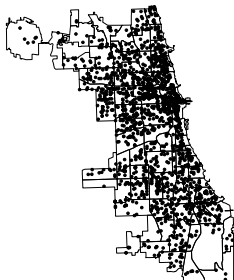
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Recap and Preview: Gaussian Processes

- ▶ Fully Bayesian framework: uncertainty intervals for all parameters, predictions, and forecasts
- ▶ Flexible and interpretable models for spatial and temporal dependencies
- ▶ Generalizes spatial approaches (heat maps) and temporal approaches (autoregressive models, periodic models)

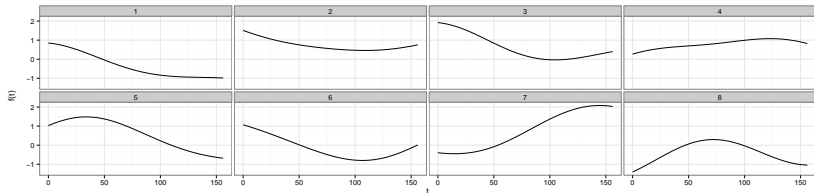
Application: Theft in Chicago

week (t)	neighborhood (s)	# of thefts
1	1	1
1	2	7
2	1	0
2	2	3
⋮	⋮	⋮



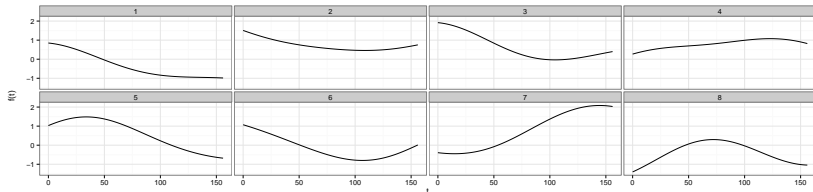
Time Component

► $k_{\text{smooth}}(t, t') = \sigma_1^2 \exp(-\frac{1}{\ell_1^2}(t - t')^2)$

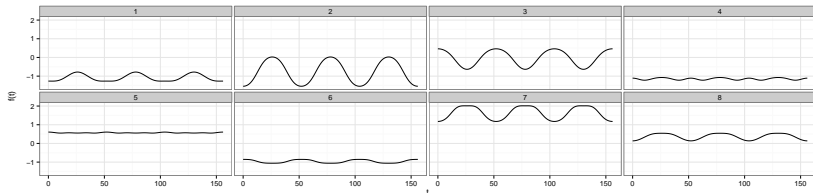


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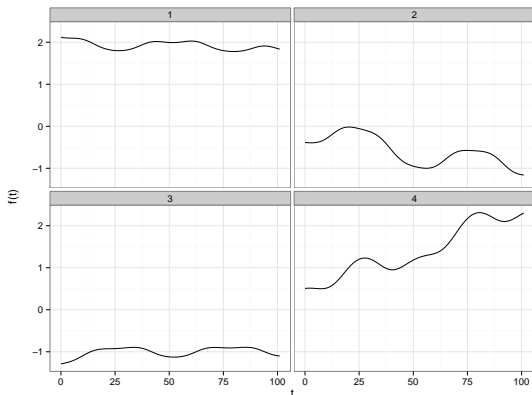


► $k_{\text{periodic}}(t, t') = \sigma_2^2 \exp\left(-\frac{1}{\ell_2^2} \sin^2\left(\frac{(t-t')\pi}{52}\right)\right)$



Time Component

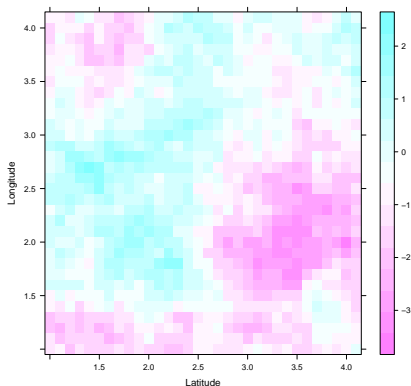
$$k(t, t') = k_{\text{smooth}}(t, t') + k_{\text{periodic}}(t, t')$$



Spatial Component

Given locations $\{s_1, \dots, s_n\}$, specify Matérn covariance:

$$k(s, s') = \sigma^2 \left(1 + \frac{\|s - s'\| \sqrt{3}}{\ell} \right) \exp \left(-\frac{\|s - s'\| \sqrt{3}}{\ell} \right)$$



Theft in Chicago

Hyperparameters:

$$\ell_1, \dots, \ell_3, \sigma_1, \dots, \sigma_5 \sim \text{Student-t}(\nu = 4)$$

Parameters:

$$k_{\text{space}}(s, s') = \text{Matern}_{\ell_1, \sigma_1^2}(s, s')$$

$$k_{\text{time}}(s, s') = \ell_2 \exp\left(-\frac{1}{\sigma_2} \|s - s'\|^2\right)$$

$$k_{\text{periodic}}(s, s') = \text{Periodic}_{\ell_3, \sigma_3^2}(s, s')$$

$$k_{\text{space-periodic}}((s, t), (s', t')) = \ell_4 \exp\left(-\frac{1}{\sigma_4} \|s - s'\|^2\right) \cdot \text{Periodic}_{1, \sigma_5^2}(t, t')$$

Latent Risk Surface:

$$f(s, t) \sim \mathcal{GP}(0, k_{\text{space}} + k_{\text{time}} + k_{\text{periodic}} + k_{\text{space-periodic}})$$

Data:

$$n_{s,t} \sim \text{Poisson}(\exp(f(s, t)))$$

Experiments and Results

- ▶ Fit full spatiotemporal model to week-neighborhood counts of theft from January 2011 to September 2013

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- ▶ Perform posterior predictive checks for predictions, variances

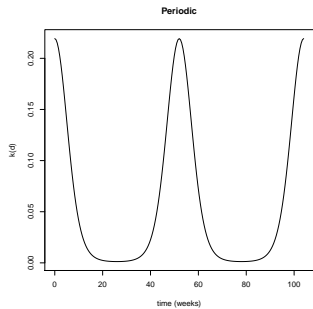
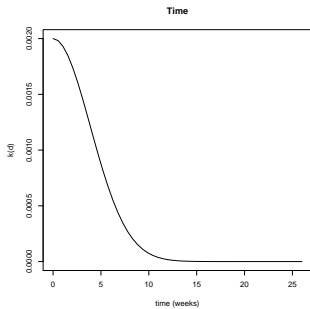
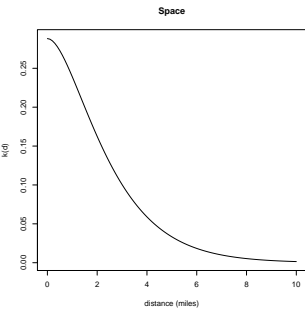
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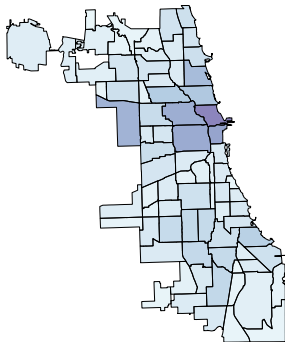
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- ▶ Calculate mean squared error of predictions (in-sample) and forecasts (out-of-sample)
- ▶ Compare to competing methods

Results

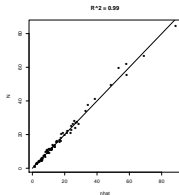
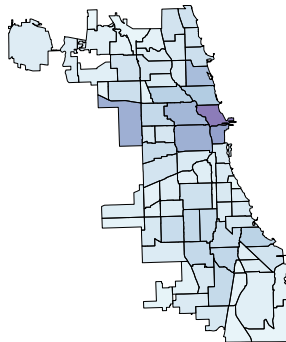


Predictions: January - June 2011

Observed

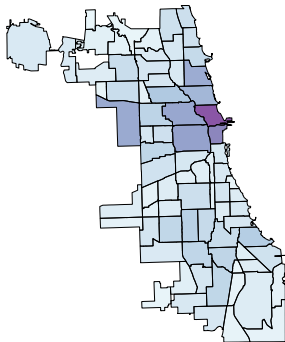


Predicted

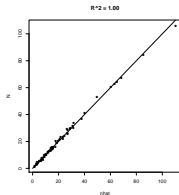
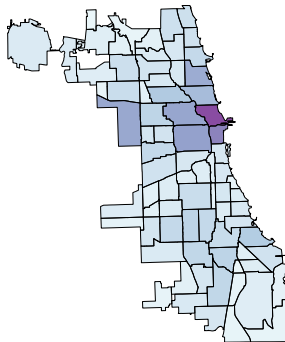


Predictions: July - December 2011

Observed

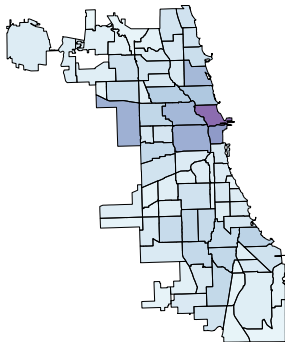


Predicted

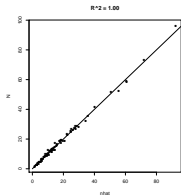
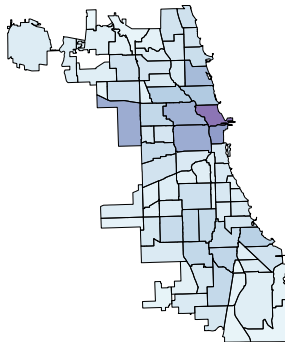


Predictions: January - June 2012

Observed

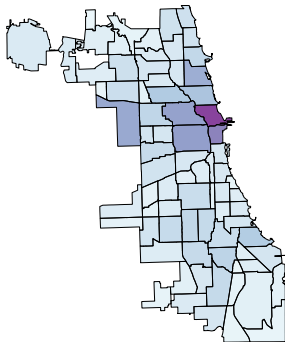


Predicted



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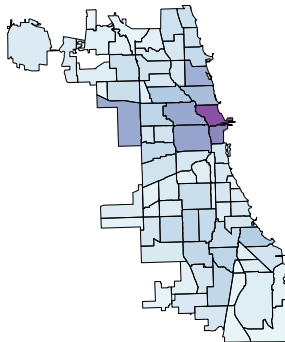
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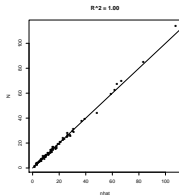
N



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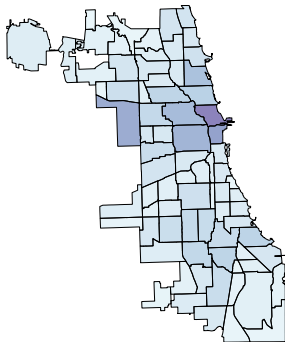


nhat

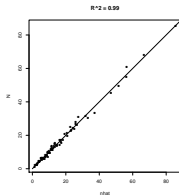
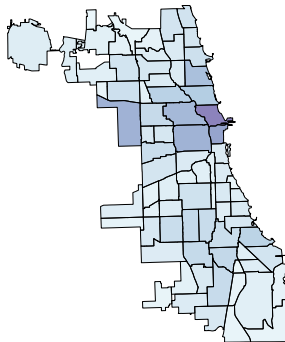


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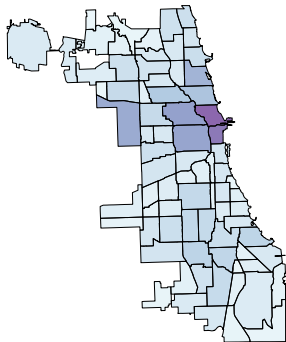


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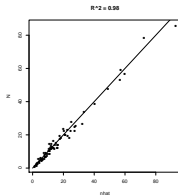
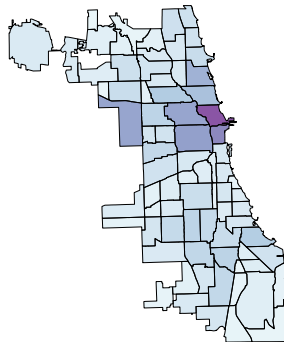


Forecasts: October - December 2013

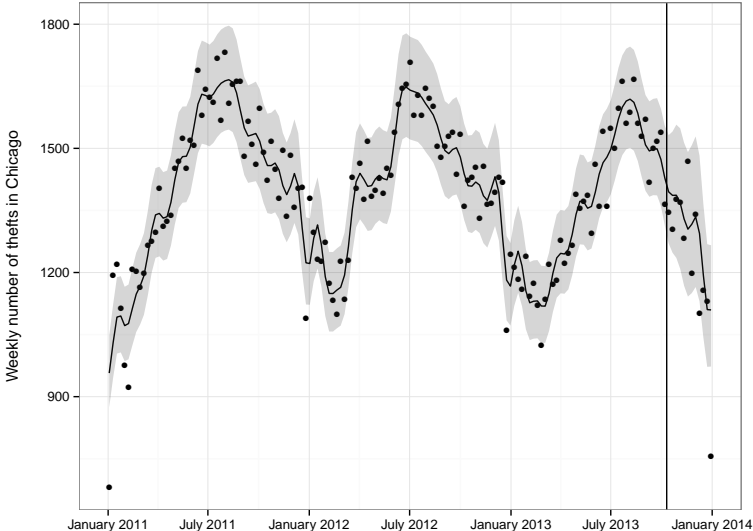
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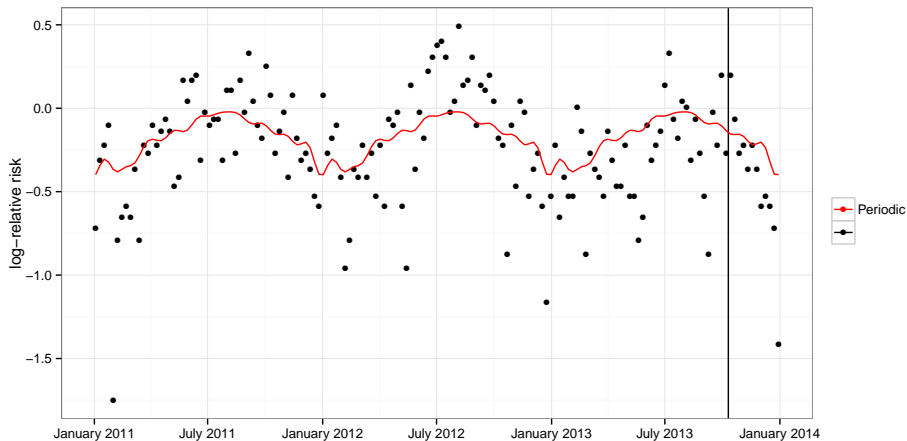
Predicted



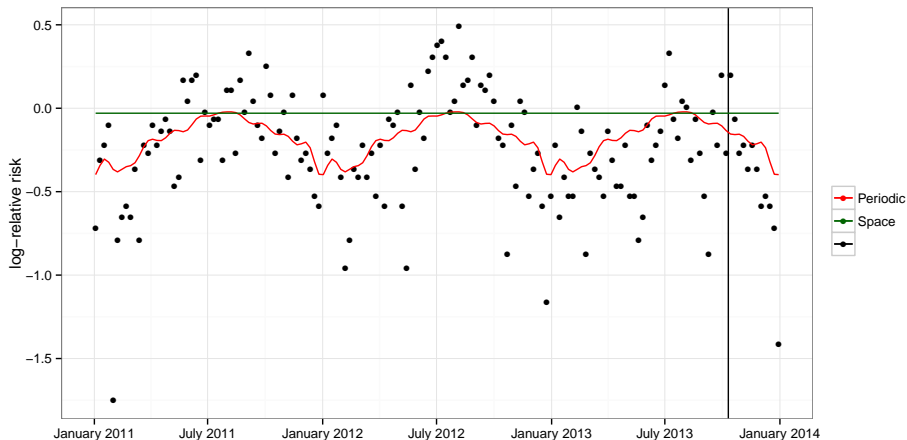
Results: Time



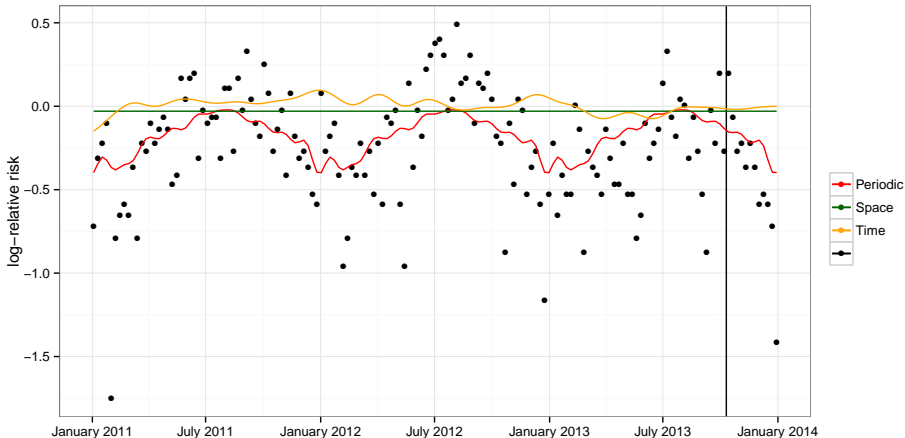
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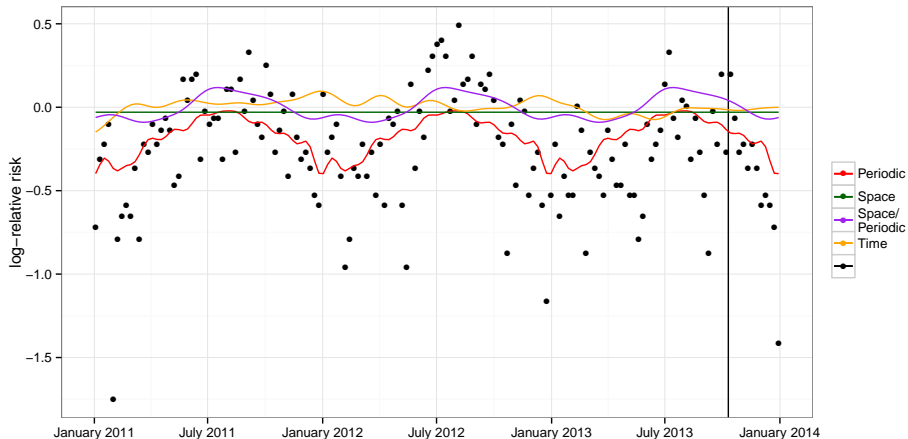
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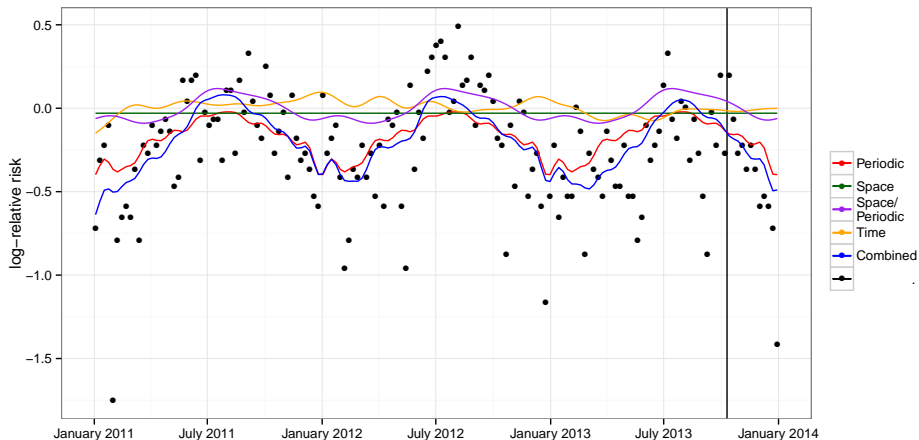
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- ▶ Future work: continuous changepoint models, more extensive comparisons to existing methods, jointly fitting different types of crimes, more applied work to understand how well-calibrated forecasts are

Thanks!

