

Mehryar Mohri
 Foundations of Machine Learning
 Courant Institute of Mathematical Sciences
 Homework assignment 2
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A. Rademacher complexity - properties

Let H be a hypothesis set reduced to two functions: $H = \{h_{-1}, h_{+1}\}$ and let $S = (x_1, \dots, x_m) \subseteq \mathcal{X}$ be a sample of size m .

1. Assume that h_{-1} is the constant function taking value -1 and h_{+1} the constant function taking the value $+1$. What is the VC-dimension d of H ? Upper bound the empirical Rademacher complexity $\mathfrak{R}_S(H)$ (*hint: express $\mathfrak{R}_S(H)$ in terms of the absolute value of a sum of Rademacher variables and apply Jensen's inequality*) and compare your bound with $\sqrt{d/m}$.

Solution: $\text{VCdim}(H) = 1$ since H can shatter one point and clearly at most one. Observe that

$$\sup_{h \in H} \sum_{i=1}^m \sigma_i h(x_i) = \sup_{h \in H} \left(\sum_{i=1}^m \sigma_i \right) h(x_1) = \left| \sum_{i=1}^m \sigma_i \right|. \quad (1)$$

Thus, by Jensen's inequality,

$$\begin{aligned} \mathfrak{R}_S(H) &= \frac{1}{m} \mathbb{E}_{\sigma} \left[\left| \sum_{i=1}^m \sigma_i \right| \right] \\ &\leq \frac{1}{m} \left[\mathbb{E}_{\sigma} \left[\left(\sum_{i=1}^m \sigma_i \right)^2 \right] \right]^{1/2} \\ &= \frac{1}{m} \left[\mathbb{E}_{\sigma} \left[\sum_{i=1}^m \sigma_i^2 \right] \right]^{1/2} \quad (\mathbb{E}[\sigma_i \sigma_j] = 0 \text{ for } i \neq j) \\ &= \frac{1}{\sqrt{m}}. \end{aligned}$$

By the Khintchine inequality, the upper bound is tight modulo the constant $1/\sqrt{2}$. The upper bound coincides with $\sqrt{d/m}$. \square

2. Assume that h_{-1} is the constant function taking value -1 and h_{+1} the function taking value -1 everywhere except at x_1 where it takes the value $+1$. What is the VC-dimension d of H ? Compute the empirical Rademacher complexity $\mathfrak{R}_S(H)$.

Solution: $\text{VCdim}(H) = 1$ since H can shatter x_1 and clearly at most one point. By definition,

$$\begin{aligned}\mathfrak{R}_S(H) &= \frac{1}{m} \mathbb{E}_{\sigma} \left[\sup_{h \in H} \sum_{i=1}^m \sigma_i h(x_i) \right] \\ &= \frac{1}{m} \mathbb{E}_{\sigma} \left[\sup_{h \in H} \sigma_1 h(x_1) - \sum_{i=2}^m \sigma_i \right] \\ &= \frac{1}{m} \mathbb{E}_{\sigma_1} \left[\sup_{h \in H} \sigma_1 h(x_1) \right] \quad (\mathbb{E}[\sigma_i] = 0) \\ &= \frac{1}{m} \mathbb{E}_{\sigma_1} [1] = \frac{1}{m}.\end{aligned}$$

Here $\mathfrak{R}_S(H)$ is a clearly more favorable quantity than $\sqrt{d/m} = \sqrt{1/m}$. \square

B. Rademacher complexity bound

Let G be a family of functions mapping from Z to $[0, 1]$. The general Rademacher complexity bound presented in class was based on the analysis of the function Φ defined by $\Phi(S) = \sup_{g \in G} \mathbb{E}[g] - \widehat{\mathbb{E}}_S[g]$ for any training sample $S = (z_1, \dots, z_m)$ of size m , with $\widehat{\mathbb{E}}_S[g] = \frac{1}{m} \sum_{i=1}^m g(z_i)$. Instead, apply McDiarmid's inequality to Ψ defined by $\Psi(S) = \sup_{g \in G} \mathbb{E}[g] - \widehat{\mathbb{E}}_S[g] - 2\mathfrak{R}_S(G)$ and try to obtain a slightly better generalization bound than the one obtained in class in terms of the empirical Rademacher complexity.

Solution: Let S' be a sample differing from S by one point, say z_m . Then, since a difference of suprema is upper bounded by the supremum of the differences, we

can write

$$\begin{aligned}
\Psi(S') - \Psi(S) &= \sup_{g \in G} (E[g] - \hat{E}_{S'}[g]) - \sup_{g \in G} (E[g] - \hat{E}_S[g]) + \frac{2}{m} E_{\sigma} \left[\sup_{g \in G} \sum_{i=1}^m \sigma_i g(z_i) - \sup_{g \in G} \sum_{i=1}^m \sigma_i g(z'_i) \right] \\
&\leq \sup_{g \in G} (E[g] - \hat{E}_{S'}[g]) - (E[g] - \hat{E}_S[g]) + \frac{2}{m} E_{\sigma} \left[\sup_{g \in G} \sum_{i=1}^m \sigma_i g(z_i) - \sum_{i=1}^m \sigma_i g(z'_i) \right] \\
&= \sup_{g \in G} \frac{1}{m} (g(z_m) - g(z'_m)) + 2 E_{\sigma} \left[\frac{1}{m} \sup_{g \in G} \sigma_m (g(z_m) - g(z'_m)) \right] \leq \frac{3}{m}.
\end{aligned}$$

Thus, by McDiarmid's inequality, $\Pr[\Psi(S) - E[\Psi(S)] > \epsilon] \leq \exp(-\frac{2}{9} m \epsilon^2)$.

Thus, for any $\delta > 0$, with probability at least $1 - \delta$,

$$\forall g \in G, \Psi(S) - E[\Psi(S)] \leq 3 \sqrt{\frac{\log \frac{1}{\delta}}{2m}}. \quad (2)$$

By definition, $E[\Psi(S)] = E[\Phi(S)] - 2\mathfrak{R}_m(G)$. In class, we showed that $E[\Phi(S)] \leq 2\mathfrak{R}_m(G)$. Thus, with probability at least $1 - \delta$, $\Psi(S) \leq \sqrt{\frac{\log \frac{1}{\delta}}{2m}}$, that is

$$\forall g \in G, E[g] \leq \hat{E}_S[g] + 2\hat{\mathfrak{R}}_S(G) + 3 \sqrt{\frac{\log \frac{1}{\delta}}{2m}}. \quad (3)$$

C. VC-dimension of union of k intervals.

What is the VC-dimension of subsets of the real line formed by the union of k intervals?

Solution:

The VC-dimension of this class is $2k$. It is not hard to see that any $2k$ distinct points on the real line can be shattered using k intervals; it suffices to shatter each of the k pairs of consecutive points with an interval. Assume now that $2k + 1$ distinct points $x_1 < \dots < x_{2k+1}$ are given. For any $i \in [1, 2k + 1]$, label x_i with $(-1)^{i+1}$, that is alternatively label points with 1 or -1 . This leads to $k + 1$ points labeled positively and requires $2k + 1$ intervals to shatter the set, since no interval can contain two consecutive points. Thus, no set of $2k + 1$ points can be shattered by k intervals, and the VC-dimension of the union of k intervals is $2k$. \square

D. Generalization bound based on covering numbers.

Let H be a family of functions mapping \mathcal{X} to a subset of real numbers $\mathcal{Y} \subseteq \mathbb{R}$. For any $\epsilon > 0$, the *covering number* $\mathcal{N}(H, \epsilon)$ of H for the L_∞ norm is the minimal

$k \in \mathbb{N}$ such that H can be covered with k balls of radius ϵ , that is, there exists $\{h_1, \dots, h_k\} \subseteq H$ such that, for all $h \in H$, there exists $i \leq k$ with $\|h - h_i\|_\infty = \max_{x \in \mathcal{X}} |h(x) - h_i(x)| \leq \epsilon$. In particular, when H is a compact set, a finite covering can be extracted from a covering of H with balls of radius ϵ and thus $\mathcal{N}(H, \epsilon)$ is finite.

Covering numbers provide a measure of the complexity of a class of functions: the larger the covering number, the richer is the family of functions. The objective of this problem is to illustrate this by proving a learning bound in the case of the squared loss. Let D denote a distribution over $\mathcal{X} \times \mathcal{Y}$ according to which labeled examples are drawn. Then, the generalization error of $h \in H$ for the squared loss is defined by $R(h) = \mathbb{E}_{(x,y) \sim D}[(h(x) - y)^2]$ and its empirical error for a labeled sample $S = ((x_1, y_1), \dots, (x_m, y_m))$ by $\hat{R}(h) = \frac{1}{m} \sum_{i=1}^m (h(x_i) - y_i)^2$. We will assume that H is bounded, that is there exists $M > 0$ such that $|h(x) - y| \leq M$ for all $(x, y) \in \mathcal{X} \times \mathcal{Y}$. The following is the generalization bound proven in this problem:

$$\Pr_{S \sim D^m} \left[\sup_{h \in H} |R(h) - \hat{R}(h)| \geq \epsilon \right] \leq \mathcal{N}\left(H, \frac{\epsilon}{8M}\right) 2 \exp\left(\frac{-m\epsilon^2}{2M^4}\right). \quad (4)$$

The proof is based on the following steps.

1. Let $L_S = R(h) - \hat{R}(h)$, then show that for all $h_1, h_2 \in H$ and any labeled sample S , the following inequality holds:

$$|L_S(h_1) - L_S(h_2)| \leq 4M \|h_1 - h_2\|_\infty.$$

Solution: First split the term into two separate terms:

$$\begin{aligned} |L_S(h_1) - L_S(h_2)| &\leq |R(h_1) - R(h_2)| + |\hat{R}(h_1) - \hat{R}(h_2)| \\ &= \left| \mathbb{E}_{x,y} [(h_1(x) - y)^2 - (h_2(x) - y)^2] \right| + \left| \frac{1}{m} \sum_{i=1}^m (h_1(x_i) - y_i)^2 - (h_2(x_i) - y_i)^2 \right|. \end{aligned}$$

Then, expanding the term

$$\begin{aligned} (h_1(x) - y)^2 - (h_2(x) - y)^2 &= (h_1(x) - h_2(x))(h_1(x) + h_2(x) - 2y) \\ &= (h_1(x) - h_2(x))((h_1(x) - y) + (h_2(x) - y)) \leq \|h_1 - h_2\|_\infty 2M, \end{aligned}$$

allows us to bound both the empirical and true error, resulting in a total bound of $4M \|h_1 - h_2\|_\infty$. \square

2. Assume that H can be covered by k subsets B_1, \dots, B_k , that is $H = B_1 \cup \dots \cup B_k$. Then, show that, for any $\epsilon > 0$, the following upper bound holds:

$$\Pr_{S \sim D^m} \left[\sup_{h \in H} |L_S(h)| \geq \epsilon \right] \leq \sum_{i=1}^k \Pr_{S \sim D^m} \left[\sup_{h \in B_i} |L_S(h)| \geq \epsilon \right].$$

Solution: This follows by splitting the event into the union of several smaller events and then using the sum rule,

$$\begin{aligned} \Pr_S \left[\sup_{h \in H} |L_S(h)| \geq \epsilon \right] \\ = \Pr_S \left[\bigvee_{i=1}^k \sup_{h \in B_i} |L_S(h)| \geq \epsilon \right] \leq \sum_{i=1}^k \Pr_S \left[\sup_{h \in B_i} |L_S(h)| \geq \epsilon \right]. \end{aligned}$$

□

3. Finally, let $k = \mathcal{N}(H, \frac{\epsilon}{8M})$ and let B_1, \dots, B_k be balls of radius $\epsilon/(8M)$ centered at h_1, \dots, h_k covering H . Use part (a) to show that for all $i \in [1, k]$,

$$\Pr_{S \sim D^m} \left[\sup_{h \in B_i} |L_S(h)| \geq \epsilon \right] \leq \Pr_{S \sim D^m} \left[|L_S(h_i)| \geq \frac{\epsilon}{2} \right],$$

and apply Hoeffding's inequality to prove (4).

Solution: For any i let h_i be the center of ball B_i with radius $\frac{\epsilon}{8M}$. Note that for any $h \in H$ we have $|L_S(h) - L_S(h_i)| \leq 4M\|h - h_i\|_\infty \leq \epsilon/2$. Thus, if for any $h \in B_i$ we have $|L_S(h)| \geq \epsilon$ it must be the case that $|L_S(h_i)| \geq \epsilon/2$, which shows the inequality.

To complete the bound, we use Hoeffding's inequality applied to the random variables $(h(x_i) - y_i)^2/m \leq M^2/m$, which guarantees

$$\Pr_S \left[|L_S(h_i)| \geq \frac{\epsilon}{2} \right] \leq 2 \exp \left(\frac{-m\epsilon^2}{2M^4} \right).$$

□