# Speech Recognition Lecture 2: Finite Automata and Finite-State Transducers

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#### **Preliminaries**

- Finite alphabet  $\Sigma$ , empty string  $\epsilon$ .
- $\blacksquare$  Set of all strings over  $\Sigma$ :  $\Sigma^*$  (free monoid).
- Length of a string  $x \in \Sigma^* : |x|$ .
- Mirror image or reverse of a string  $x = x_1 \cdots x_n$ :

$$x^R = x_n \cdots x_1.$$

 $\blacksquare$  A language L: subset of  $\Sigma^*$ .

# Rational Operations

- Rational operations over languages:
  - union: also denoted  $L_1 + L_2$ ,

$$L_1 \cup L_2 = \{x \in \Sigma^* : x \in L_1 \lor x \in L_2\}.$$

concatenation:

$$L_1 \cdot L_2 = \{ x = uv \in \Sigma^* : u \in L_1 \lor v \in L_2 \}.$$

closure:

$$L^* = \bigcup_{n=0}^{\infty} L^n$$
, where  $L^n = \underbrace{L \cdots L}_n$ .

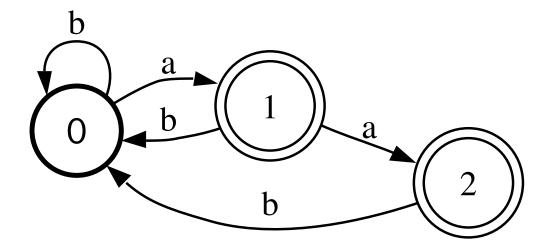
# Regular or Rational Languages

- lacktriangle Definition: closure under rational operations of  $\Sigma^*$ . Thus,  $\mathrm{Rat}(\Sigma^*)$  is the smallest subset  $\mathcal L$  of  $2^{\Sigma^*}$ verifying
  - ullet  $\emptyset \in \mathcal{L}$  :
  - $\bullet \ \forall x \in \Sigma^*, \{x\} \in \mathcal{L}$ :
  - $\bullet \ \forall L_1, L_2 \in \mathcal{L}, L_1 \cup L_2 \in \mathcal{L}, L_1 \cdot L_2 \in \mathcal{L}, L_1^* \in \mathcal{L}.$
- **Examples** of regular languages over  $\Sigma = \{a, b, c\}$ :
  - $\Sigma^*$ ,  $(a+b)^*c$ ,  $ab^nc$ ,  $(a+(b+c)^*ba)^*cb$ .

#### Finite Automata

- Definition: a finite automaton A over the alphabet  $\Sigma$  is 4-tuple (Q, I, F, E) where Q is a finite set of states,  $I \subseteq Q$  a set of initial states,  $F \subseteq Q$  a set of final states, and E a multiset of transitions which are elements of  $Q \times (\Sigma \cup \{\epsilon\}) \times Q$ .
  - a path  $\pi$  in an automaton A = (Q, I, F, E) is an element of  $E^*$ .
  - a path from a state in I to a state in F is called an accepting path. Language L(A) accepted by A: set of strings labeling accepting paths.

# Finite Automata - Example

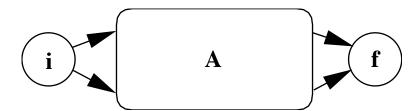


# Finite Automata - Some Properties

- Trim: any state lies on some accepting path.
- Unambiguous: no two accepting paths have the same label.
- Deterministic: unique initial state, two transitions leaving the same state have different labels.
- Complete: at least one outgoing transition labeled with any alphabet element at any state.
- Acyclic: no path with a cycle.

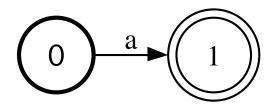
#### Normalized Automata

- Definition: a finite automaton is normalized if
  - it has a unique initial state with no incoming transition.
  - it has a unique final state with no outgoing transition.



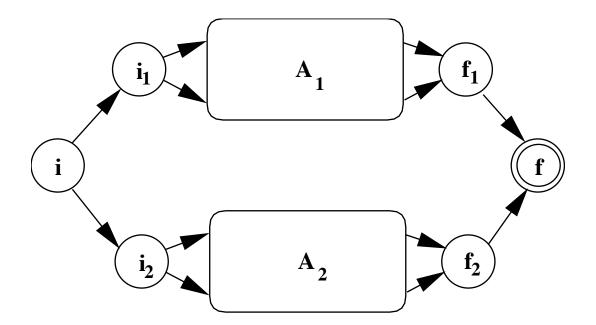
# Elementary Normalized Automaton

■ Definition: normalized automaton accepting an element  $a \in \Sigma \cup \{\epsilon\}$  constructed as follows.



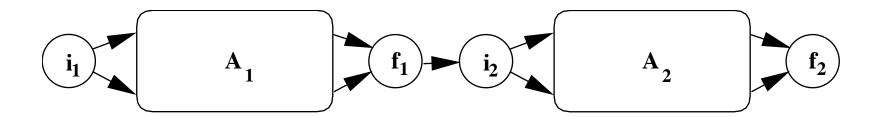
#### Normalized Automata: Union

Construction: the union of two normalized automata is a normalized automaton constructed as follows.



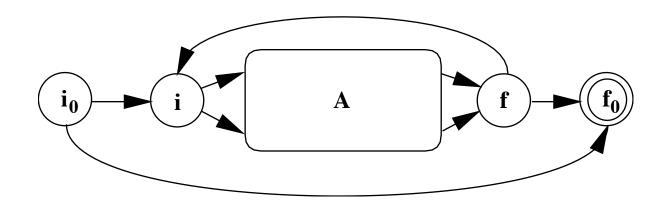
#### Normalized Automata: Concatenation

Construction: the concatenation of two normalized automata is a normalized automaton constructed as follows.



#### Normalized Automata: Closure

Construction: the closure of a normalized automaton is a normalized automaton constructed as follows.



# Normalized Automata - Properties

- Construction properties:
  - each rational operation require creating at most two states.
  - each state has at most two outgoing transitions.
  - the complexity of each operation is linear.

# Thompson's Construction

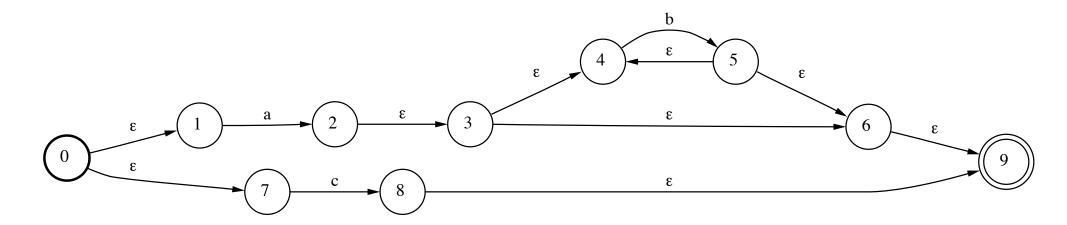
(Thompson, 1968)

Proposition: let r be a regular expression over the alphabet  $\Sigma$ . Then, there exists a normalized automaton A with at most 2|r| states representing r.

#### Proof:

- linear-time context-free parser to parse regular expression.
- construction of normalized automaton starting from elementary expressions and following operations of the tree.

# Thompson's Construction - Example



Normalized automaton for regular expression  $ab^* + c$ .

## Regular Languages and Finite Automata

(Kleene, 1956)

- Theorem: A language is regular iff it can be accepted by a finite automaton.
- Proof: Let A = (Q, I, F, E) be a finite automaton.
  - for  $(i,j,k)\in [1,|Q|]\times [1,|Q|]\times [0,|Q|]$  define  $X_{ij}^k=\{i\to q_1\to q_2\to\ldots\to q_n\to j:n\ge 0,q_i\le k\}.$
  - $X_{ij}^0$  is regular for all (i,j) since E is finite.
  - by recurrence  $X_{ij}^k$  for all (i, j, k) since

$$X_{ij}^{k+1} = X_{ij}^k + X_{i,k+1}^k (X_{k+1,k+1}^k)^* X_{k+1,j}^k.$$

•  $L(A) = \bigcup_{i \in I, f \in F} X_{if}^{|Q|}$  is thus regular.

# Regular Languages and Finite Automata

Proof: the converse holds by Thompson's construction.

#### Notes:

- a more general theorem (Schützenberger, 1961) holds for weighted automata.
- not all languages are regular, e.g.,  $L = \{a^n b^n : n \in \mathbb{N}\}$ is not regular. Let A be an automaton. If  $L \subseteq L(A)$ , then for large enough  $n, a^n b^n$  corresponds to a path with a cycle:  $a^nb^n=a^pub^q$ ,  $a^pu^*b^q\subseteq L(A)$ , which implies  $L(A) \neq L$ .

# Left Syntactic Congruence

lacktriangle Definition: for any language  $L\subseteq \Sigma^*$  , the left syntactic congruence is the equivalence relation defined by

$$u \equiv_L v \Leftrightarrow u^{-1}L = v^{-1}L,$$

where for any  $u \in \Sigma^*$ ,  $u^{-1}L$  is defined by

$$u^{-1}L = \{w \colon uw \in L\}.$$

•  $u^{-1}L$  is sometimes called the partial derivative of L with respect to u and denoted  $\frac{\partial L}{\partial u}$ .

# Regular Languages - Characterization

- **Theorem:** a language L is regular iff the set of  $u^{-1}L$ is finite ( $\equiv_L$  has a finite index).
- Proof: let A = (Q, I, F, E) be a trim deterministic automaton accepting L (existence seen later).
  - let  $\delta$  the partial transition function. Then,

$$u R v \Leftrightarrow \delta(i, u) = \delta(i, v).$$

also defines an eq. relation with index |Q|.

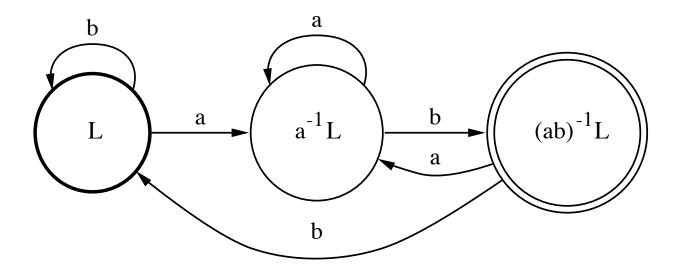
• since  $\delta(i, u) = \delta(i, v) \Rightarrow u^{-1}L = v^{-1}L$ , the index of  $\equiv_L$  is at most |Q|, thus finite.

# Regular Languages - Characterization

- Proof: conversely, if the set of  $u^{-1}L$  is finite, then the automaton A = (Q, I, F, E) defined by
  - $Q = \{u^{-1}L : u \in \Sigma^*\};$
  - $i = \epsilon^{-1}L = L \cdot I = \{i\}$ :
  - $F = \{u^{-1}L : u \in L\}$ ;
  - $E = \{(u^{-1}L, a, (ua)^{-1}L) : u \in \Sigma^*\}$ ; is well defined since  $u^{-1}L = v^{-1}L \Rightarrow (ua)^{-1}L = (va)^{-1}L$  and accepts exactly L.

#### Illustration

■ Minimal deterministic automaton for  $(a + b)^*ab$ :

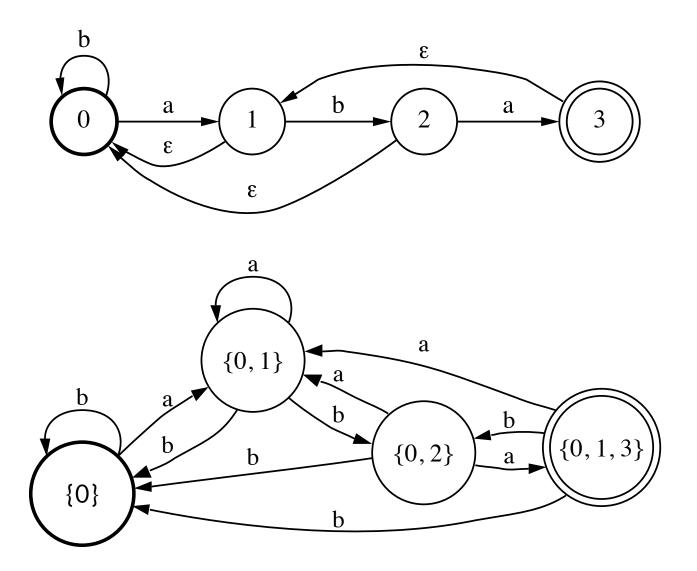


#### **E-Removal**

- Theorem: any finite automaton A = (Q, I, F, E) admits an equivalent automaton with no  $\epsilon$ -transition.
- Proof: for any state  $q \in Q$ , let  $\epsilon[q]$  denote the set of states reached from q by paths labeled with  $\epsilon$ . Define A' = (Q', I', F', E') by

  - $\bullet \ E' = \{ (\epsilon[p], a, \epsilon[q]) : \exists (p', a, q') \in E, p' \in \epsilon[p], q' \in \epsilon[q] \}.$

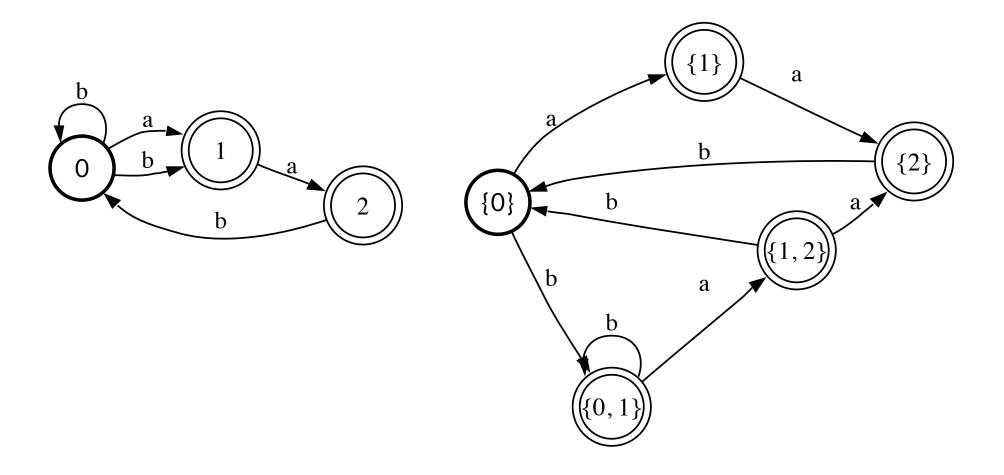
### **E-Removal - Illustration**



#### Determinization

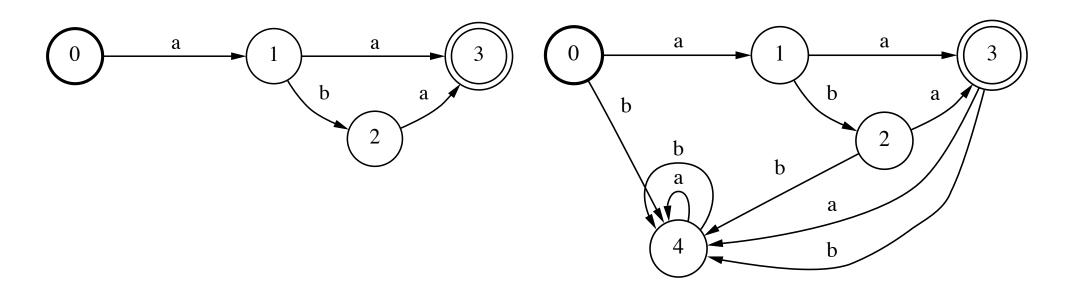
- Theorem: any automaton A = (Q, I, F, E) without  $\epsilon$ -transitions admits an equivalent deterministic automaton.
- Proof: Subset construction: A' = (Q', I', F', E') with
  - $Q' = 2^Q$ .
  - $\bullet I' = \{ s \in Q' \colon s \cap I \neq \emptyset \}.$
  - $\bullet F' = \{ s \in Q' \colon s \cap F \neq \emptyset \}.$
  - $E' = \{(s, a, s') : \exists (q, a, q') \in E, q \in s, q' \in s'\}$ .

#### Determinization - Illustration



# Completion

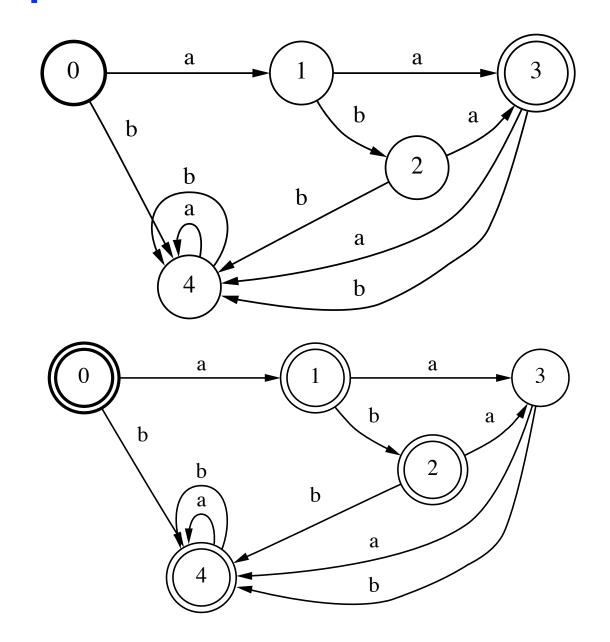
- Theorem: any deterministic automaton admits an equivalent complete deterministic automaton.
- Proof: constructive, see example.



# Complementation

- **Theorem:** let A = (Q, I, F, E) be a deterministic automaton, then there exists a deterministic automaton accepting L(A).
- $\blacksquare$  Proof: by a previous theorem, we can assume Acomplete. The automaton  $B = (\Sigma, Q, I, Q - F, E)$ obtained from A by making non-final states final and final states non-final exactly accepts L(A).

# Complementation - Ilustration



# Regular Languages - Properties

- Theorem: regular languages are closed under rational operations, intersection, complementation, reversal, morphism, inverse morphism, and quotient with any set.
- Proof: closure under rational operations holds by definition.
  - intersection: use De Morgan's law.
  - complementation: use algorithm.
  - others: algorithms and equivalence relation.

#### Rational Relations

- Definition: closure under rational operations of the monoid  $\Sigma^* \times \Delta^*$ , where  $\Sigma$  and  $\Delta$  are finite alphabets, denoted by  $\operatorname{Rat}(\Sigma^* \times \Delta^*)$ .
  - examples:  $(a, b)^*$ ,  $(a, b)^*(bb, a) + (b, a)$ .

#### Rational Relations - Characterization

(Nivat, 1968)

■ Theorem:  $R \subseteq \operatorname{Rat}(\Sigma^* \times \Delta^*)$  is a rational relation iff there exists a regular language  $L \subseteq (\Sigma \cup \Delta)^*$  such that

$$R = \{(\pi_{\Sigma}(x), \pi_{\Delta}(x)) : x \in L\}$$

where  $\pi_{\Sigma}$  is the projection of  $(\Sigma \cup \Delta)^*$  over  $\Sigma^*$ and  $\pi_{\Delta}$  the projection over  $\Delta^*$ .

Proof: use surjective morphism

$$\pi: (\Sigma \cup \Delta)^* \to (\Sigma^* \times \Delta^*)$$
$$x \to (\pi_{\Sigma}(x), \pi_{\Delta}(x)).$$

### **Transductions**

- Definition: a function  $\tau \colon \Sigma^* \to 2^{\Delta^*}$  is called a transduction from  $\Sigma^*$  to  $\Delta^*$ .
  - relation associate to  $\tau$ :

$$R(\tau) = \{(x, y) \in \Sigma^* \times \Delta^* : y \in \tau(x)\}.$$

transduction associated to a relation:

$$\forall x \in \Sigma^*, \tau(x) = \{y : (x, y) \in R\}.$$

 rational transductions: transductions with rational relations.

### Finite-State Transducers

- Definition: a finite-state transducer Tover the alphabets  $\Sigma$  and  $\Delta$  is 4-tuple where Q is a finite set of states,  $I \subseteq Q$  a set of initial states,  $F \subseteq Q$  a set of final states, and E a multiset of transitions which are elements of  $Q \times (\Sigma \cup \{\epsilon\}) \times (\Delta \cup \{\epsilon\}) \times Q$ .
  - ullet T defines a relation via the pair of input and output labels of its accepting paths,

$$R(T) = \{(x, y) \in \Sigma^* \times \Delta^* : I \xrightarrow{x:y} F\}.$$

#### Rational Relations and Transducers

- Theorem: a transduction is rational iff it can be realized by a finite-state transducer.
- Proof: Nivat's theorem combined with Kleene's theorem, and construction of a normalized transducer from a finite-state transducer.

## References

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