# (Extended Abstract) <br> A New Constructive Root Bound for Algebraic Expressions 

Chen Li Chee Yap*<br>Courant Institute of Mathematical Sciences<br>New York University, New York, NY 10012, USA.<br>Email: \{chenli, yap\}@cs.nyu.edu

July 7, 2000


#### Abstract

Computing effective root bounds for constant algebraic expressions is a critical problem in the Exact Geometric Computation approach to robust algorithms. Classical root bounds are often non-constructive. Recently, various authors have proposed bounding methods which might be called constructive root bounds. For the important class of radical expressions, Burnikel et al (BFMS) have provided a constructive root bound which, in the division-free case, is an improvement over previously known bounds and is essentially tight. In the presence of division, their bound requires a quadratic blowup in root bit-bound compared to the division-free case. We present a new constructive root bound that avoids this quadratic blowup and which is applicable to a more general class of algebraic expressions. This leads to dramatically better performance in some computations. We also give an improved version of the degree-measure bound from Mignotte and BFMS. We describe our implementation in the context of the Core Library, and report on some experimental results.


## 1 Introduction

There is considerable recent interest in robust implementation of geometric algorithms [17, 14]. Exact Geometric Computation (EGC) [19] is one general approach to achieve robust algorithms. This is the approach in, for instance, the LEDA $[3,8]$ and CGAL [6] libraries. A fundamental task in EGC is to determine the exact sign of a constant algebraic expression $E$. For example, the following expression arises in the implementation of Fortune's sweepline algorithm [5] for the Voronoi diagram of a planar point set:

$$
\begin{equation*}
E=\frac{a+\sqrt{b}}{d}-\frac{a^{\prime}+\sqrt{b^{\prime}}}{d^{\prime}}, \tag{1}
\end{equation*}
$$

where $a, a^{\prime}, b, b^{\prime}, d, d^{\prime}$ are integer constants. Typically, the sign determination task reduces to first finding some root bound $b$ for $E$. We call $b>0$ a root bound for $E$ if the following holds: if $E \neq 0$ then $|E| \geq b$. With this root bound, we can determine the sign of $E$ by computing a numerical approximation $\widetilde{E}$ such that $|E-\widetilde{E}|<\frac{b}{2}$. The sign of $E$ is the same as that of $\widetilde{E}$ if $|\widetilde{E}| \geq \frac{b}{2}$,

[^0]otherwise we can conclude that $E=0$. In practice [19], the precision required in approximation can be progressively increased until one of two events occurs: either (i) the approximation $\widetilde{E}$ satisfies $|\widetilde{E}|>|E-\widetilde{E}|$, or (ii) the approximation satisfies $|E-\widetilde{E}|<\frac{b}{2}$. Note that if $|E|$ is large, then condition (i) will be reached first, and the root bound does not play a role in the actual complexity of the sign determination. However, if $E$ is zero (as happens in, say, degenerate cases or theorem proving application [15]), then the root bound plays a critical role. The Real/Expr Package [19] is the first system to systematically exploit such root bounds. More recently, the LEDA Library [1] and the Core Library [9, 7] have made such sign determination techniques easily accessible to any programmer.

The problem of root bounds and more generally, root location, is a very classical one with an extensive literature (e.g., [10] or [12, chap. 2]). We are mainly interested in bounding roots away from 0 . Some classical bounds are highly non-constructive. If a bound for a root $\alpha$ of a polynomial $P(x)$ is given in terms of some simple function of $P$ 's coefficients and degree, it can be considered constructive. For instance, Landau's bound says that any non-zero root $\alpha$ of $P(x)$ satisfies $|\alpha| \geq\|P(x)\|_{2}^{-1}$ where $P(x)=\sum_{i=0}^{n} a_{i} x^{i}$ and $\|P(x)\|_{2}=\sqrt{\sum_{i=0}^{n}\left|a_{i}\right|^{2}}$. Unfortunately, in many applications, the coefficients of $P(x)$ are not explicitly given. For instance, in the LEDA and Core libraries, an algebraic number $\alpha$ is presented as a radical expression which is constructed from the integers, and recursively built-up using the four arithmetic operations $(+,-, \times, \div)$ and radical extraction $\sqrt[k]{\cdot}(k \geq 2)$. Thus, the notion of "constructive" depends on the presentation of $\alpha$; we call such a presentation an expression. If $E$ is a presentation of $\alpha$, we will write $\operatorname{val}(E)=\alpha$. The constructive root bound problem is this: given a set $\mathcal{E}$ of expressions (e.g., the radical expressions), give a set of inductive rules for computing a root bound for each expression in $\mathcal{E}$. If $b$ is a root bound for an expression $E$, we will call $-\log _{2} b$ a root bit-bound for $E$. In the worst case, the root bit-bound determines the complexity of our sign determination algorithms. It is important to realize that in our paper, the term "expression" roughly corresponds to a directed acyclic graph in which nodes are labeled by the appropriate constants and operations (see Section 3).

One of the best constructive root bounds for the class of radical expressions is from Burnikel et al [2] (hereafter called the "BFMS bound"). The BFMS approach is based on a well-known transformation of an expression $E$ to eliminate all but one division, producing two associated division-free expressions $U(E)$ and $L(E)$ such that $\operatorname{val}(E)=\operatorname{val}(U(E)) / \operatorname{val}(L(E))$. If $E$ is divisionfree, then $L(E)=1$ and $\operatorname{val}(E)$ is an algebraic integer. For an expression $E$ having $r$ radical nodes with indices $k_{1}, k_{2}, \ldots, k_{r}$, the BFMS bound is given by

$$
\begin{equation*}
\operatorname{val}(E) \neq 0 \Rightarrow|\operatorname{val}(E)| \geq\left(u(E)^{D(E)^{2}-1} l(E)\right)^{-1} \tag{2}
\end{equation*}
$$

where $D(E)=\prod_{i=1}^{r} k_{i}$, and $u(E)$ and $l(E)$ are (respectively) upper bounds on the absolute values of algebraic conjugates of $\operatorname{val}(U(E))$ and $\operatorname{val}(L(E))$. For division-free expressions, the BFMS bound improves to

$$
\begin{equation*}
\operatorname{val}(E) \neq 0 \Rightarrow|\operatorname{val}(E)| \geq\left(u(E)^{D(E)-1}\right)^{-1} \tag{3}
\end{equation*}
$$

This was shown to be essentially sharp. Note that the root bit-bound in (2) is quadratic in $D(E)$, while in (3), it is linear in $D(E)$. Our experience is that this quadratic factor can be a serious efficiency issue. Consider a simple example: $E=(\sqrt{x}+\sqrt{y})-\sqrt{x+y+2 \sqrt{x y}}$ where $x, y$ are $L$-bit integers (i.e., $|x|,|y|<2^{L}$ ). Of course, this expression is identically 0 for any $x, y$. The BFMS bound yields a root bit-bound of $7.5 L+\mathcal{O}(1)$ bits. But in case, $x$ and $y$ are viewed as rational numbers (with denominator 1 ), the bit-bound becomes $127.5 L+\mathcal{O}(1)$. The example shows that introducing rational numbers at the leaves of expressions has a major impact on the

BFMS bound. In practice, this is an important and common situation: for instance, it is usual to have floating point numbers as input constants in an expression. Since these are special cases of rational numbers, the BFMS bound becomes quite pessimistic.

Main Results. In this paper, we address two issues raised by the BFMS bound. First, is the quadratic factor $D(E)^{2}$ in the root bit-bound of $E$ essential for radical expressions? We show that it is not: $D(E)$ is sufficient. However, this requires a new approach in which we also need to maintain, among other things, upper bounds on the leading as well as tail coefficients of the minimal polynomial of the algebraic number $E$. The second issue is whether the BFMS technique can be extended to more general algebraic expressions. For instance, suppose we introduce a new kind of leaves into our expressions denoted by $\operatorname{Root}(P(x))$ where $P(x)$ is an integer polynomial. Our new approach can handle this kind of extension. But the framework of BFMS cannot handle this extension since there is no analogue of the $E \mapsto(U(E), L(E))$ transformation.

For any algebraic number $\alpha$, we will exploit the following relation:

$$
\begin{equation*}
\alpha \neq 0 \Rightarrow|\alpha| \geq\left(\mu(\alpha)^{\operatorname{deg}(\alpha)-1} \operatorname{lead}(\alpha)\right)^{-1}, \tag{4}
\end{equation*}
$$

where $\mu(\alpha)=\max \{|\xi|: \xi$ is a conjugate of $\alpha\}, \operatorname{deg}(\alpha)$ is the degree of the minimal polynomial $\operatorname{Irr}(\alpha)$ of $\alpha$ and lead $(\alpha)$ is the leading coefficient of $\operatorname{Irr}(\alpha)$.

For radical expressions without divisions, our new bound turns out to be exactly same as the BFMS bound; but for those with divisions, our root bit-bound is only linear in $D(E)$. To see the effects of this improvement, recall the expression in Fortune's algorithm given in (1). Suppose the inputs to Fortune's algorithm are $L$-bit integers. Then it can be shown that the bit lengths for $a$ and $a^{\prime}$ are $3 L$, for $b$ and $b^{\prime}$ are $6 L$ and for $d$ and $d^{\prime}$ are $2 L$. The BFMS bit-bound for this predicate is $(79 L+30)$ bits. Our new bit-bound gives $(19 L+9)$ bits. Sellen and Yap [16] have shown that $15 L+O(1)$ bits are sufficient, and this is the best possible.

Improved degree-measure bound. Mignotte and Burnikel et al [2, 11, 12] presented a constructive root bound, called the degree-measure bound. As a side product of our new root bound, we obtain improvements to this degree-measure bound. This can lead to much improved performance, as seen in our theorem proving application [15].
Overview of Paper. In Section 2, we review previous work on constructive root bounds. Section 3 formalizes the constructive root bound problem. We present our new constructive root bound in Section 4, and give an improved degree-measure bound in Section 5. In Section 6, experimental results are reported. We conclude in Section 7.

## 2 Previous Work

A number of constructive root bounds have been proposed. Here we briefly recall some of them.
Canny's bound. For a zero-dimensional system $\Sigma$ of $n$ polynomial equations with $n$ unknowns, Canny [4] shows that if $\left(\alpha_{1}, \ldots, \alpha_{n}\right)$ is a solution, then $\left|\alpha_{i}\right| \geq(3 d c)^{-n d^{n}}$ for each non-zero component $\alpha_{i}$. Here $c$ (resp., $d$ ) is an upper bound on the absolute value of coefficients (resp., the degree) of any polynomial in the system. An important proviso in Canny's bound is that the homogenized system $\widehat{\Sigma}$ has a non-vanishing $U$-resultant. See Yap [18, p. 350 ] for the general treatment, based on the notion of "generalized $U$-resultant". Such multivariate root bounds are
easily translated into a bound on expressions, as discussed in [2].
Degree-length and degree-height bounds. The degree-length bound [18] is a general bound for algebraic expressions, based on Landau's root bound. A similar degree-height bound based on Cauchy's root bound is found in [19]. Here "length" and "height" refer to the 2-norm and $\infty$-norm of a polynomial, respectively. These results are based on the resultant calculus.

Degree-measure bound. Given a polynomial $P(x)=a_{m} \prod_{i=1}^{m}\left(x-\alpha_{i}\right)$, with $a_{m} \neq 0$, the measure of $P, m(P)$, is defined as $\left|a_{m}\right| \cdot \prod_{i=1}^{m} \max \left\{1,\left|\alpha_{i}\right|\right\}$. Furthermore, the measure $m(\alpha)$ of an algebraic number $\alpha$ is defined as the measure of $\operatorname{Irr}(\alpha)$. It is known that if $\alpha \neq 0$, we have $\frac{1}{m(\alpha)} \leq|\alpha| \leq m(\alpha)$. Based on Mignotte's work, Burnikel et al [2] develop recursive rules to maintain the upper bounds for degrees and measures and call it the degree-measure bound. These rules are given in the last two columns of Table 3 where $M^{\prime}(E)$ and $D^{\prime}(E)$ are (respectively) upper bounds on $m(E)$ and $\operatorname{deg}(E)$. Similar rules are given in [12]. The degree-measure bound turns out to be always better than the degree-length bound.

BFMS bound. Burnikel et al [2] discovered a bound for radical expressions (see (2) and (3)). Their bound for division-free expressions (3) is proved to be better than any of the previous bounds. But in presence of divisions, the BFMS bound is not necessarily a strict improvement of the above bounds.

Scheinerman bound. This adopts an interesting approach based on matrix eigenvalues [13]. Let $\Lambda(n, b)$ denote the set of eigenvalues of $n \times n$ matrices with integer entries with absolute value at most $b$. It is easy to see that $\Lambda(n, b)$ is a finite set of algebraic integers. Moreover, if $\alpha \in \Lambda(n, b)$ is non-zero then $|\alpha| \geq(n b)^{1-n}$. Scheinerman gives a constructive root bound for division-free radical expressions $E$ by maintaining two parameters, $n(E)$ and $b(E)$, satisfying the property that the value of $E$ is in $\Lambda(n(E), b(E))$. These recursive rules are given by the following table.

|  | $E$ | $n(E)$ | $b(E)$ |
| :---: | :---: | :---: | :---: |
| 1. | integer $a$ | 1 | $\|a\|$ |
| 2. | $\sqrt{a b}$ | 2 | $\max \{\|a\|,\|b\|\}$ |
| 3. | $E_{1} \pm E_{1}$ | $n_{1} n_{2}$ | $b_{1}+b_{2}$ |
| 4. | $E_{1} \times E_{1}$ | $n_{1} n_{2}$ | $b_{1} b_{2}$ |
| 5. | $\sqrt[k]{E_{1}}$ | $k n_{1}$ | $b_{1}$ |
| 6. | $P\left(E_{1}\right)$ | $n_{1}$ | $\bar{P}(n b)$ |

Note that the rule for $\sqrt{a b}$ is rather special, but it can be extremely useful. In Rule 6 , the polynomial $\bar{P}(x)$ is given by $\sum_{i=0}^{d}\left|a_{i}\right| x^{i}$ when $P(x)=\sum_{i=0}^{d} a_{i} x^{i}$. This rule is not explicitly stated in [13], but can be deduced from an example he gave. An example given in [13] is to test whether $\alpha=\sqrt{2}+\sqrt{5-2 \sqrt{6}}-\sqrt{3}$ is zero. Scheinerman's bound requires calculating $\alpha$ to 39 digits while the BFMS bound says 12 digits are enough.

## 3 The General Framework

We formalize the constructive root bound problem as follows. For the purposes of this paper, a "DAG" is an ordered, directed acyclic graph with a unique node that has out-degree 0 , called the root. The DAG is ordered in the sense that the set of incoming edges to each node $u$ is given a total ordering. Nodes with in-degree 0 are called leaves. Let $\Omega$ be a set of algebraic operations:
each $\omega \in \Omega$ represents a partial function $f_{\omega}: \mathbb{C}^{k} \rightarrow \mathbb{C}$ where $\mathbb{C}$ are the complex numbers and $k=k(\omega)$ is called the arity of $\omega$. If $k(\omega)=0$ then $\omega$ may be identified with an element of $\mathbb{C}$ and is called a constant. An expression over $\Omega$ (or $\Omega$-expression) is a DAG where each node $u$ of in-degree $k_{u}$ is labeled by an operation $\omega \in \Omega$ where $k(\omega)$ equals the in-degree of $u$. In particular the leaves are labeled by constants. In case ${ }^{1}$ the DAG is a tree, then we call it a tree expression. Each node in an expression induces a natural subexpression. Let $\mathcal{E}(\Omega)$ denote the set of $\Omega$-expressions. The following classes of expressions are the main ones in this paper:

- $\Omega_{0}=\{ \pm, \times\} \cup \mathbb{Z}$ (where $\mathbb{Z}$ are the integers). Thus $\Omega_{0}$-expressions are polynomials.
- $\Omega_{1}=\Omega_{0} \cup\{\div\}$. Thus $\Omega_{1}$-expressions are rational expressions.
- $\Omega_{2}=\Omega_{1} \cup\{\sqrt[n]{\cdot}: n \geq 2\}$. Thus $\Omega_{2}$-expressions are radical expressions.
- $\Omega_{3}=\Omega_{2} \cup\{\operatorname{Root}(P): P \in \mathbb{Z}[x]\}$. Our main root bound applies to $\Omega_{3}$-expressions. We assume the polynomial $P$ is presented by its sequence of $n+1$ integer coefficients if $\operatorname{deg}(P)=$ $n$.

We need to clarify the $\operatorname{Root}(P)$ operation in $\Omega_{3}$ above. This is intended to be a constant referring to some root $\alpha$ of $P$. In practice, we will need some method for identifying the root $\alpha$. For instance, if $\alpha$ is real and is the $k$ th largest real root of $P$, we could identify $\alpha$ as " $\operatorname{Root}(P, k)$ ". Instead of $k$, we could also use, say, an isolating interval for $\alpha$. It turns out that our root bounds do not depend on the choice of the root of $P$, and hence, we normally write "Root $(P)$ " instead of "Root $(P, k)$ ".

For any set $\mathcal{E}$ of expressions, there is a partial function val : $\mathcal{E} \rightarrow \mathbb{C}$ that is naturally defined by applying the appropriate functions $f_{\omega}(\omega \in \Omega)$ at each node of an expression. We simply write " $E$ " instead of "val $(E)$ " when the context is unambiguous. All our statements about val $(E)$ are also conditioned about $\operatorname{val}(E)$ being defined. The constructive root bound problem for a class $\mathcal{E}$ of expressions is that of providing a bounding function

$$
B: \mathbb{R}^{m} \rightarrow \mathbb{R} \quad(\mathbb{R}=\text { reals })
$$

and a set of "recursive rules" to compute for each $E \in \mathcal{E}$ a set of real parameters $\left\{a_{i}(E): i=\right.$ $1, \ldots, m\}$, plus possibly other non-numeric parameters, such that the following holds:

$$
\operatorname{val}(E) \neq 0 \Rightarrow|\operatorname{val}(E)| \geq B\left(a_{1}(E), \ldots, a_{m}(E)\right)
$$

The rules are "recursive" in the sense that the parameters for each node in the DAG can be effectively computed from the parameters of its predecessors. In practice, the function $B$ will be non-negative, with both $B$ and the recursive rules relatively simple to compute. Another desirable property is that the bound $B\left(a_{1}(E), \ldots, a_{m}(E)\right)$ should be as large as possible. Also, we call $m$ the order of constructive root bound.

Example: In the degree-measure bound, we compute two parameters, $a_{1}(E)$ and $a_{2}(E)$ where $a_{1}$ and $a_{2}$ are upper bounds on the degree and measure of $E$. Moreover, the bounding function $B: \mathbb{R}^{m} \rightarrow \mathbb{R}$ is given by $B(a, b)=1 / b$ (the first parameter is ignored by $B$ ). So the order of the degree-measure bound is $m=2$.

[^1]Table 1: Recursive rules for $\operatorname{lc}(E)$ (and associated $\operatorname{tc}(E)$ and $M(E)$ )

|  | E | $\operatorname{lc}(E)$ | $\operatorname{tc}(E)$ | $M(E)$ |
| :---: | :---: | :---: | :---: | :---: |
| 1. | rational $\frac{a}{b}$ | \|b| | $\|a\|$ | $\max \{\|a\|,\|b\|\}$ |
| 2. | $\operatorname{Root}(P)$ | $\|\operatorname{lead}(P)\|$ | $\mid$ tail $(P) \mid$ | $\\|P\\|_{2}$ |
| 3. | $E_{1} \pm E_{2}$ | $\mathrm{lc}_{1}^{D_{2}} \mathrm{lc}_{2}^{D_{1}}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}} 2^{D(E)}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}} 2^{D(E)}$ |
| 4. | $E_{1} \times E_{2}$ | $\mathrm{lc}_{1}^{D_{2}} \mathrm{lc}_{2}^{D_{1}}$ | $\mathrm{tc}_{1}^{D_{2}} \mathrm{tc}_{2}^{D_{1}}$ | $M_{1}^{D_{2}^{2}} M_{2}^{D_{1}}$ |
| 5. | $E_{1} \div E_{2}$ | $\mathrm{lc}_{1}^{D_{2}} \mathrm{tc}_{2}^{D_{1}}$ | $\mathrm{tc}_{1}^{D_{2}} \mathrm{lc}_{2}^{D_{1}}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}}$ |
| 6. | $\sqrt[k]{E_{1}}$ | $\mathrm{lc}_{1}$ | $\mathrm{tc}_{1}$ | $M_{1}$ |
| 7. | $E_{1}^{k}$ | $1 c_{1}^{k}$ | $\mathrm{tc}_{1}^{k}$ | $M_{1}^{k}$ |

## 4 New Constructive Root Bound

In this section, we develop a constructive root bound for $\Omega_{3}$-expressions. In order to obtain a root bound for an expression $E$ using the relation (4), we need three parameters: $\operatorname{deg}(E), \mu(E)$ and lead $(E)$. The definitions of these parameters involve the minimal polynomial of $E$, which is usually expensive to compute. Instead, we give recursive rules to maintain upper bounds

$$
D(E), \quad \bar{\mu}(E), \quad \operatorname{lc}(E)
$$

on the corresponding parameters.
First we consider $D(E)$, using the same approach as BFMS. Suppose that $E$ has $k$ radical nodes or root-of-polynomial nodes $\left\{r_{1}, r_{2}, \ldots, r_{k}\right\}$. Assume some topological sorting $r_{1} \prec r_{2} \prec \cdots \prec r_{k}$ of these nodes so that if $r_{i}$ is a predecessor of $r_{j}$ then $i<j$. Clearly, the degree of $E$ over $\mathbb{Q}$ is no more than $\prod_{i=1}^{k} d_{i}$ where $d_{i}$ is the degree of $r_{i}$ over the extension field $\mathbb{Q}\left(r_{1}, \ldots, r_{i-1}\right)$. Define $D(E)=\prod_{i=1}^{k} k_{i}$ where $k_{i}$ is either the index of $r_{i}$ if $r_{i}$ is a radical node, or the degree of the polynomial if $r_{i}$ is a polynomial-root node. Thus, $D(E)$ is an upper bound on $\operatorname{deg}(E)$ since $d_{i} \leq k_{i}$ for all $i$.

Given a non-zero polynomial $P(x)$, we denote its leading coefficient, its tail coefficient and its constant coefficient (respectively) by lead $(P)$, $\operatorname{tail}(P)$, and const $(P)$. Note that the tail $(P)$ is defined to be the last non-zero coefficient of $P$. By definition, $\operatorname{lead}(P), \operatorname{tail}(P) \neq 0$. Also, let $m(P)$ denote the measure of $P$. Given an algebraic number $\alpha$, we define $\operatorname{lead}(\alpha)$, $\operatorname{tail}(\alpha)$ and $m(\alpha)$ as lead $(\operatorname{Irr}(\alpha))$, $\operatorname{tail}(\operatorname{Irr}(\alpha))$ and $m(\operatorname{Irr}(\alpha))$ respectively.

Bound on Leading Coefficient and Table 1. We now consider lc $(E)$, which is an upper bound on $|\operatorname{lead}(E)|$. The admission of divisions makes it necessary to bound tail coefficients as well. Moreover, we also need to bound the measure of $E$ to help bound $|\operatorname{tail}(E)|$ (this is only used when $E$ has the form $E=E_{1} \pm E_{2}$ ). Let $\operatorname{tc}(E)$ and $M(E)$ denote upper bounds on tail $(E)$ and $m(E)$. Table 1 gives the recursive rules to maintain $\operatorname{lc}(E), \operatorname{tc}(E)$ and $M(E)$.

The upper bound $M(E)$ on the measure of $E$ is shown ${ }^{2}$ in the last column. We note that the invariant $\operatorname{tc}(E) \leq M(E)$ is implicitly assumed. In other words, if the rule for $\operatorname{tc}(E)$ gives a value larger than $M(E)$, it is implicit in our rules to replace $\operatorname{tc}(E)$ by $M(E)$. Also note that we introduce a special node for the power operation $E=E_{1}^{k}$. This is not just a shortcut for ( $k-1$ ) multiplications; it leads to much better bounds too. For example, in computing $\operatorname{lc}(E)$ by

[^2]Table 2: Recursive rules for $\bar{\mu}(E)$ and $\underline{\nu}(E)$

|  | $E$ | $\bar{\mu}(E)$ | $\underline{\nu}(E)$ |
| :---: | :--- | :---: | :---: |
| 1. | $\operatorname{rational} \frac{a}{b}$ | $\left\|\frac{a}{b}\right\|$ | $\left\|\frac{a}{b}\right\|$ |
| 2. | $\operatorname{Root}(P)$ | $1+\\|P\\|_{\infty}$ | $\left(1+\\|P\\|_{\infty}\right)^{-1}$ |
| 3. | $E_{1} \pm E_{2}$ | $\bar{\mu}\left(E_{1}\right)+\bar{\mu}\left(E_{2}\right)$ | $\left(\bar{\mu}(E)^{D(E)-1} \mid \mathrm{c}(E)\right)^{-1}$ |
| 4. | $E_{1} \times E_{2}$ | $\bar{\mu}\left(E_{1}\right) \bar{\mu}\left(E_{2}\right)$ | $\underline{\nu}\left(E_{1}\right) \underline{\nu}\left(E_{2}\right)$ |
| 5. | $E_{1} \div E_{2}$ | $\bar{\mu}\left(E_{1}\right) / \underline{\nu}\left(E_{2}\right)$ | $\underline{\nu}\left(E_{1}\right) / \bar{\mu}\left(E_{2}\right)$ |
| 6. | $\sqrt[k]{E_{1}}$ | $\sqrt[k]{\bar{\mu}\left(E_{1}\right)}$ | $\sqrt[k]{\underline{\nu}\left(E_{1}\right)}$ |
| 7. | $E_{1}^{k}$ | $\bar{\mu}\left(E_{1}\right)^{k}$ | $\underline{\nu}\left(E_{1}\right)^{k}$ |

naively expanding $E$ into $(k-1)$ multiplications, we get $\mathrm{lc}(E)=\mathrm{lc}_{1}^{\left(D_{1}^{k+1}-1\right) /\left(D_{1}-1\right)} \gg \mathrm{lc}_{1}^{k}$. Similar improvements can be shown for $\operatorname{tc}(E)$ and $m(E)$.

The justification of Table 1 is omitted in this extended abstract. The basic techniques come from resultant calculus. One subtlety arises for expressions of the form $E=E_{1} \pm E_{2}$. In this case, resultant calculus gives us a polynomial $P_{E}(x)$ where $\operatorname{val}(E)$ vanishes. We can also deduce a bound on const $\left(P_{E}\right)$. Unfortunately, this constant coefficient may vanish and tell us nothing about tail $(E)$. Hence we need to resort to $m(E)$ as a bound for $|\operatorname{tail}(E)|$.

Bound on Conjugates and Table 2. Now we consider $\bar{\mu}(E)$, which is an upper bound on the absolute value of all the conjugates of $\operatorname{val}(E)$. Because of the admission of divisions, we also have to maintain $\underline{\nu}(E)$, which is a lower bound on the absolute value of all the conjugates of $\operatorname{val}(E)$ whenever $\operatorname{val}(E) \neq 0$. The recursive rules to maintain these two bounds are given in Table 2. The most noteworthy entry in Table 2 is the bound for $\underline{\nu}(E)$ when $E=E_{1} \pm E_{2}$. In this case, we use the relation (4). In practice, we might want to take the maximum of this value and $1 / M(E)$. We also note that our bounds on $\bar{\mu}(\operatorname{Root}(P))$ and $\underline{\nu}(\operatorname{Root}(P))$ are based on Cauchy's root bound [18, p. 148]. Of course, any of the classical root bounds can be used as convenient.

The justification of Table 2 is omitted in this abstract.
Finally, we obtain the new root bound in the following theorem:

Theorem 1 Given an $\Omega_{3}$-expression $E$, if $E \neq 0$, then

$$
\begin{equation*}
|E| \geq\left(\bar{\mu}(E)^{(D(E)-1)} \operatorname{lc}(E)\right)^{-1} \tag{5}
\end{equation*}
$$

By an examination of our tables, we can also assert:

Lemma 2 For a division-free radical expression $E$, our bound is exactly the same as the BFMS bound.

## 5 Improved Degree-Measure Bound

Let $E$ be a $\Omega_{3}$-expression. As explained in Section $2, M^{\prime}(E)$ and $D^{\prime}(E)$ in Table 3 are the original degree-measure bound $[11,12,2]$. Recall the definition of $D(E)$ which gives an upper bound
on $\operatorname{deg}(E)$. It is clear that $D(E)$ is never larger than $D^{\prime}(E)$. Based on $D(E)$, we now give an improved upper bound on measures (this is denoted by $M(E)$ in Table 3).

Table 3: The original and our improved degree-measure bounds

|  | $E$ | $M(E)($ new $)$ | $M^{\prime}(E)($ old $)$ | $D^{\prime}(E)$ (old) |
| :---: | :--- | :---: | :---: | :---: |
| 1. | rational $\frac{a}{b}$ | $\max \{\|a\|,\|b\|\}$ | $\max \{\|a\|,\|b\|\}$ | 1 |
| 2. | $\operatorname{Root}(P)$ | $\\|P\\|_{2}$ | - | - |
| 3. | $E_{1} \pm E_{2}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}} 2^{D(E)}$ | $M_{1}^{\prime D_{2}^{\prime}} M_{2}^{\prime} D_{1}^{\prime} 2^{D_{1}^{\prime} D_{2}^{\prime}}$ | $D_{1}^{\prime} D_{2}^{\prime}$ |
| 4. | $E_{1} \times E_{2}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}}$ | $M_{1}^{\prime} D_{2}^{\prime} M_{2}^{\prime D_{1}^{\prime}}$ | $D_{1}^{\prime} D_{2}^{\prime}$ |
| 5. | $E_{1} \div E_{2}$ | $M_{1}^{D_{2}} M_{2}^{D_{1}}$ | $M_{1}^{\prime D_{2}^{\prime}} M_{2}^{\prime D_{1}^{\prime}}$ | $D_{1}^{\prime} D_{2}^{\prime}$ |
| 6. | $\sqrt[k]{E_{1}}$ | $M_{1}$ | $M_{1}^{\prime}$ | $k D_{1}^{\prime}$ |
| 7. | $E_{1}^{k}$ | $M_{1}^{k}$ | $M_{1}^{\prime k}$ | - |

When $E=\operatorname{Root}(P)$ for some polynomial $P$, we use $\|P\|_{2}$ as the upper bound $M(E)$ because $\|P\|_{2} \geq m(P)$. Besides the introduction of the new operations of $\operatorname{Root}(P)$ and power $\left(E_{1}^{k}\right)$ in Table 3, we give a slightly improved rule for the measure of $E_{1} \pm E_{2}$. Basically, we can replace the factor of $2^{D_{1}^{\prime} D_{2}^{\prime}}$ by $2^{D}$. Here is the justification:

Lemma 3 If $\alpha$ and $\beta$ are algebraic numbers with degrees $m$, $n$, respectively, then the measure of $\alpha \pm \beta$ is bounded by $2^{d} m(\alpha)^{n} m(\beta)^{m}$ where $d=\operatorname{deg}(\alpha \pm \beta)$.

Proof is omitted for this abstract.
The improvement can be significant when there is sharing of subexpressions. For example, consider $E=((\sqrt{x}+\sqrt{y})-2 \sqrt{x+y+2 \sqrt{x} \sqrt{y}}) \cdot((\sqrt{x}+\sqrt{y})+2 \sqrt{x+y+2 \sqrt{x} \sqrt{y}})$ where $x$ and $y$ are $L$-bit integers. The original degree-measure bound for $E$ is $2^{3584 L+7148}$. But when all the common subexpressions of $E$ are merged, our new bound gives $2^{896 L+1408}$.

## 6 Experimental Results

The new constructive root bound has been implemented in our Core Library [7]. Our experiments, based on version 1.2 x of the Core library, will mainly compare the performances of our new bound and the BFMS bound. All the tests are performed on a Sun Ultra 250 with two UltraSPARC-II 296 MHz CPUs and 512 MB main memory. All timings are in seconds.

1. Recall the critical test in Fortune's sweepline algorithm is to determine the sign of the expression $E=\frac{a+\sqrt{b}}{d}-\frac{a^{\prime}+\sqrt{b^{\prime}}}{d^{\prime}}$ in Equation (1) where $a\left(\right.$ or $\left.a^{\prime}\right), b\left(\right.$ or $\left.b^{\prime}\right)$ and $d$ (or $d^{\prime}$ ) are $3 L-, 6 L$ - and $2 L$-bit integers, respectively. Our root bit-bound improves the BFMS bound from $(79 L+30)$ bits to to $(19 L+9)$ bits. We generate some random inputs with different $L$ values which always make $E=0$, and put the timings of the tests in Table 4. We also converted the Fortune's implementation of

Table 4: Timings for Fortune's expression in (1)

| $L$ | 10 | 20 | 30 | 50 | 100 | 200 |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| BFMS | 0.08 | 0.52 | 2.51 | 4.06 | 28.1 | 218.76 |
| NEW | 0.02 | 0.08 | 0.22 | 0.32 | 1.72 | 11.73 |

this algorithm to use Core library. We ran the program on two kinds of inputs: (1) First we test on a non-degenerate data set (100 random points provided in Fortune's code distribution). The time for our new bound is 7.87 seconds while the BFMS bound takes 7.96 seconds. This is not unexpected, since as explained in the introduction, our Core library exploits the precisiondriven technique, and the signs of Fortune's predicate on non-degenerate inputs can be determined without reaching the root bounds. (2) We used highly degenerate inputs comprising points on a $(32 \times 32)$ uniform grid with coordinates being $L$ bits long. The timings are reported in Table 5 .

Table 5: Timings for Fortune's algorithm on degenerate inputs

| $L$ | 10 | 20 | 30 | 50 |
| :---: | ---: | ---: | ---: | ---: |
| BFMS | 212.02 | 1929.27 | 2830.90 | 9948.63 |
| NEW | 83.90 | 217.37 | 232.99 | 404.11 |

2. Consider the expression $E=\frac{a+b^{2^{-r}}}{c}-\frac{d+e^{2^{-r}}}{f}$ with $2 r(r \geq 1)$ square roots. The BFMS root bit-bound is $\left(5 \cdot 2^{4 r}-1\right) L+2\left(2^{4 r}-1\right)$, while our new bound gives $2 \cdot 2^{2 r} L+3\left(2^{2 r}-1\right)$ bits. Table 6 gives a comparison on these two root bit-bounds, when $L=10$ and $r=1,2,5,10$. Our experiment shows that when $L=10, r=2$ and $E=0$, sign determination using our new bound takes 5.99 seconds; while with the BFMS bound the test program does not terminate within 2 hours.

Table 6: Root bit-bounds (in bits) when $L=10$

| $r$ | 1 | 2 | 5 | 10 |
| :---: | ---: | ---: | ---: | ---: |
| BFMS | 820 | 13300 | 54525940 | $5.7 \cdot 10^{13}$ |
| NEW | 199 | 835 | 54259 | $5.6 \cdot 10^{7}$ |

3. The third test is to verify an expression which is identically zero. Let $x=\frac{a}{b}$ and $y=\frac{c}{d}(a, b, c, d$ are $L$-bit integers), and $E=(\sqrt{x}+\sqrt{y})-\sqrt{x+y+2 \sqrt{x y}}$. Our new bound requires computing $(40 L+38)$ bits, while the BFMS requires $(640 L+510)$ bits. The timings are in Table 7.

Table 7: Timings for Example 3

| $L$ | 5 | 10 | 20 | 30 |
| :---: | ---: | ---: | ---: | ---: |
| BFMS | 1830.61 | 8768.29 | $>3 \mathrm{hrs}$ | $>3 \mathrm{hrs}$ |
| NEW | 0.71 | 3.17 | 17.04 | 55.43 |

In comparing the timings of BFMS with our new method, it is the relative speedup that should be stressed. We expect similar relative improvements to show up if the comparisons were made in other systems such as LEDA.

## 7 Conclusion

We have described a new constructive root bound for a large class of algebraic expressions. The main achievement is that our root bit-bound is only linear in the algebraic degree (or some upper bound thereof) of the expression.

We implemented it in our Core library and our experiments show remarkable speedup over the

BFMS bound in many cases. Although we have described our bounds for the class of $\Omega_{3^{-}}$ expressions, it should be clear that our methods extend to more general expressions.

A challenge for the future work is to find better ways of bounding $\operatorname{tc}(E)$ for addition and subtraction nodes. The current bound on tail coefficients based on the polynomial measure seems to be too conservative for expressions with complex structure and large depth. Also, it may be possible to improve our current bound on $\underline{\nu}\left(E_{1} \pm E_{2}\right)$.

## References

[1] C. Burnikel, R. Fleischer, K. Mehlhorn, and S. Schirra. Exact geometric computation made easy. In Proc. 15th ACM Symp. Comp. Geom., pages 341-450, 1999.
[2] C. Burnikel, R. Fleischer, K. Mehlhorn, and S. Schirra. A strong and easily computable separation bound for arithmetic expressions involving radicals. Algorithmica, 27:87-99, 2000.
[3] C. Burnikel, J. Könnemann, K. Mehlhorn, S. Näher, S. Schirra, and C. Uhrig. Exact geometric computation in LEDA. In Proc. 11th ACM Symp. Computational Geom., pages C18-C19, 1995.
[4] J. F. Canny. The complexity of robot motion planning. ACM Doctoral Dissertion Award Series. The MIT Press, 1988. PhD thesis, M.I.T.
[5] S. J. Fortune. A sweepline algorithm for Voronoi diagrams. Algorithmica, 2:153-174, 1987.
[6] The CGAL Homepage. Computational Geometry Algorithms Library (CGAL) Project. URL http://www.cs.uu.nl/CGAL/.
[7] The CORE Project Homepage. URL http://www.cs.nyu.edu/exact/.
[8] LEDA Homepage. Library of Efficient Data Structures and Algorithms (LEDA) Project. URL http://www.mpi-sb.mpg.de/LEDA/.
[9] V. Karamcheti, C. Li, I. Pechtchanski, and C. Yap. A Core Library for robust numeric and geometric computation. In Proc. 15th ACM Symp. on Computational Geometry, pages 351-359, June 1999. Florida.
[10] M. Marden. The geometry of the zeroes of a polynomial in a complex variable. American Mathematical Society, 1949.
[11] M. Mignotte. Identification of algebraic numbers. Journal of Algorithms, 3(3), 1982.
[12] M. Mignotte and D. Ştefănescu. Polynomials: An Algorithmic Approach. Springer, 1999.
[13] E. R. Scheinerman. When close enough is close enough. American Mathematical Monthly, 107:489-499, 2000.
[14] S. Schirra. Robustness and precision issues in geometric computation. Research Report MPI-I-98-1004, Max-Planck-Institut für Informatik, Saarbrücken, Germany, January 1996.
[15] D. Tulone, C. Yap, and C. Li. Randomized zero testing of radical expressions and elementary geometry theorem proving. Submitted for publication. Paper available at URL http://cs.nyu.edu/exact/doc/, June 2000.
[16] C. Yap. Lecture notes in robust geometric computation, 2000 . URL http://www.cs.nyu.edu/~yap/classes/exact/.
[17] C. K. Yap. Robust geometric computation. In J. E. Goodman and J. O'Rourke, editors, Handbook of Discrete and Computational Geometry, chapter 35, pages 653-668. CRC Press LLC, 1997.
[18] C. K. Yap. Fundamental Problems in Algorithmic Algebra. Oxford Univ. Press, Aug. 1999.
[19] C. K. Yap and T. Dubé. The exact computation paradigm. In D.-Z. Du and F. K. Hwang, editors, Computing in Euclidean Geometry, pages 452-486. World Scientific Press, 1995. 2nd edition.


[^0]:    *This work is supported in part by NSF Grant \#CCR-9619846.

[^1]:    ${ }^{1}$ In some literature, our tree expressions are simply called "expressions" while our expressions are essentially "straightline programs" or "circuits".

[^2]:    ${ }^{2}$ This information is copied from column 2 in Table 3, and is discussed in conjunction with that table.

